

OFFSHORE WIND TURBINE FOUNDATIONS

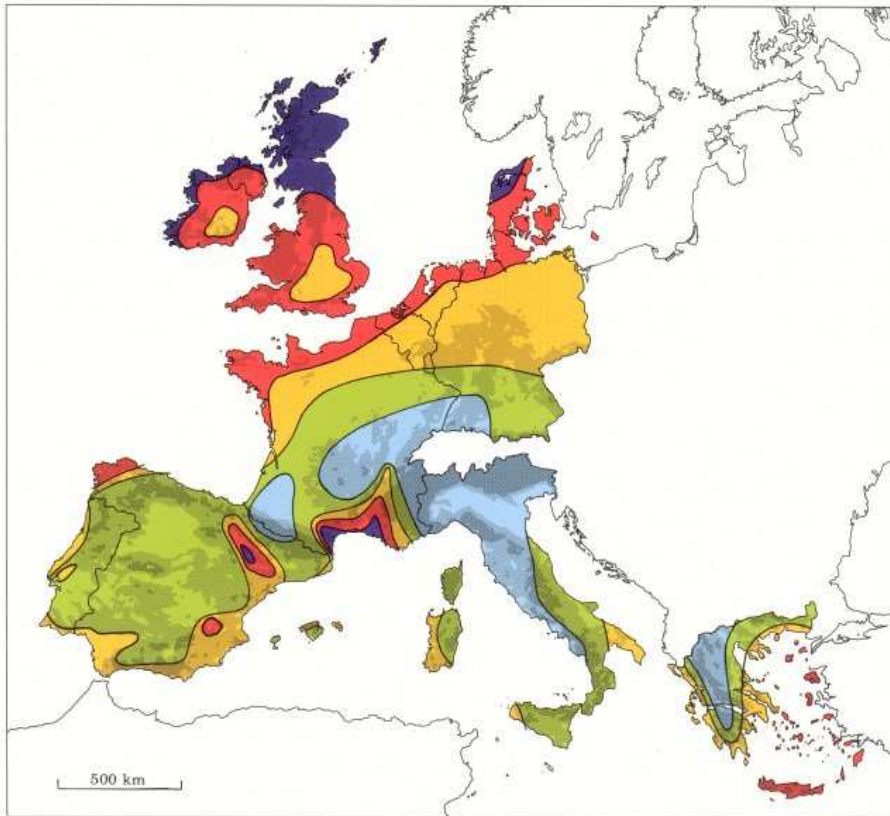
Christophe PEYRARD

EDF R&D - LNHE

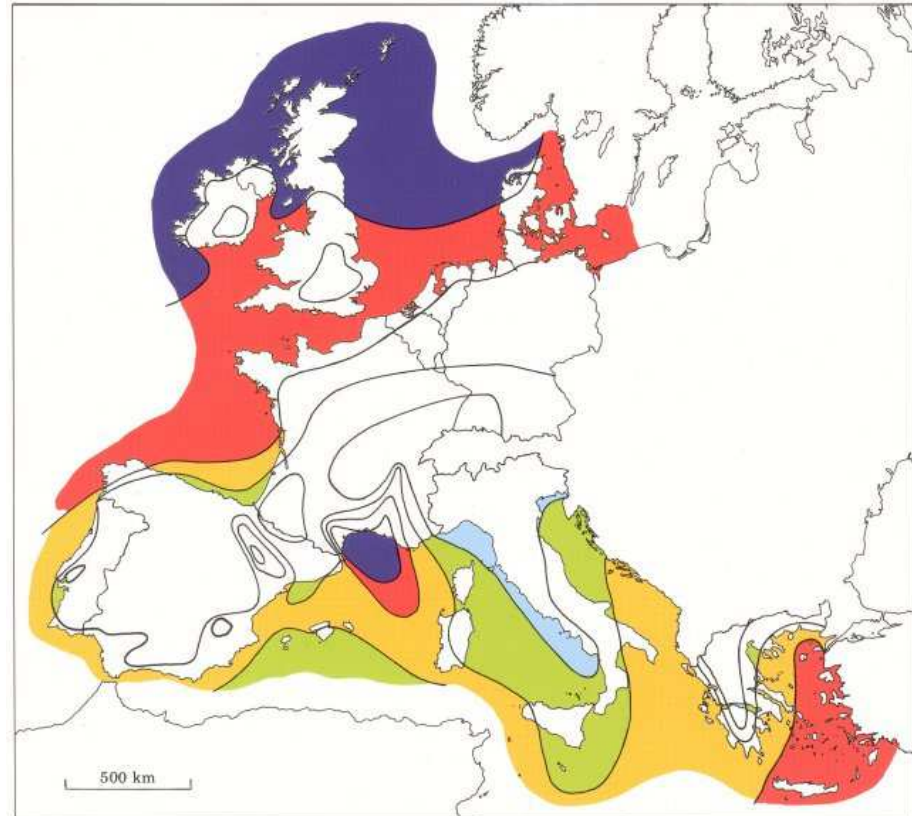
Laboratoire d'Hydraulique St Venant



WIND RESOURCE IN EUROPE



Wind resources ¹ at 50 metres above ground level for five different topographic conditions									
Sheltered terrain ²		Open plain ³		At a sea coast ⁴		Open sea ⁵		Hills and ridges ⁶	
$m s^{-1}$	Wm^{-2}	$m s^{-1}$	Wm^{-2}	$m s^{-1}$	Wm^{-2}	$m s^{-1}$	Wm^{-2}	$m s^{-1}$	Wm^{-2}
> 6.0	> 250	> 7.5	> 500	> 8.5	> 700	> 9.0	> 800	> 11.5	> 1800
5.0-6.0	150-250	6.5-7.5	300-500	7.0-8.5	400-700	8.0-9.0	600-800	10.0-11.5	1200-1800
4.5-5.0	100-150	5.5-6.5	200-300	6.0-7.0	250-400	7.0-8.0	400-600	8.5-10.0	700-1200
3.5-4.5	50-100	4.5-5.5	100-200	5.0-6.0	150-250	5.5-7.0	200-400	7.0- 8.5	400- 700
< 3.5	< 50	< 4.5	< 100	< 5.0	< 150	< 5.5	< 200	< 7.0	< 400



Wind resources over open sea (more than 10 km offshore) for five standard heights									
10 m		25 m		50 m		100 m		200 m	
$m s^{-1}$	Wm^{-2}	$m s^{-1}$	Wm^{-2}	$m s^{-1}$	Wm^{-2}	$m s^{-1}$	Wm^{-2}	$m s^{-1}$	Wm^{-2}
> 8.0	> 600	> 8.5	> 700	> 9.0	> 800	> 10.0	> 1100	> 11.0	> 1500
7.0-8.0	350-600	7.5-8.5	450-700	8.0-9.0	600-800	8.5-10.0	650-1100	9.5-11.0	900-1500
6.0-7.0	250-300	6.5-7.5	300-450	7.0-8.0	400-600	7.5- 8.5	450- 650	8.0- 9.5	600- 900
4.5-6.0	100-250	5.0-6.5	150-300	5.5-7.0	200-400	6.0- 7.5	250- 450	6.5- 8.0	300- 600
< 4.5	< 100	< 5.0	< 150	< 5.5	< 200	< 6.0	< 250	< 6.5	< 300

From the *European Wind Atlas*. Copyright © 1989 by Risø National Laboratory, Denmark

OFFSHORE WIND ENERGY



OBJECTIVES OF THE PRESENTATION

- **Offshore Wind Energy**
 - Development / General context
 - Bottom fixed context in France
 - Floating context in France
- **Bottom fixed / Floating foundations**
 - Engineering
 - Construction
 - Installation
- **Technical aspects and challenges**



OFFSHORE WIND CONTEXT



OFFSHORE WIND - HISTORY

- 1st offshore wind turbine installed in Sweden in 1991 (Nogersund; 220kW Wind World W2500; Ø 25 m).
- 1st offshore wind farm in Denmark in 1992 (off Vindeby; 11 x 450 kW Bonus B35/450). Water depth: 2 - 4 m; gravity foundation; 3km from shore.
- Until 2001, various developments off Denmark, Sweden and Netherlands (turbines P < 1MW).
- Denmark started to develop large offshore wind farms:
 - Middelgrunden (2001): 40MW; 20 x Bonus B76 – 2MW turbines.
 - Horns Rev I (2002): 160 MW ; 80 x Vestas V80-2MW
 - Nysted (2003): 166 MW; 72 x Siemens SWT 2.3MW turbines
- Since 2003, the UK then Germany and Belgium have launched large offshore wind projects...



OFFSHORE WIND DEVELOPMENT

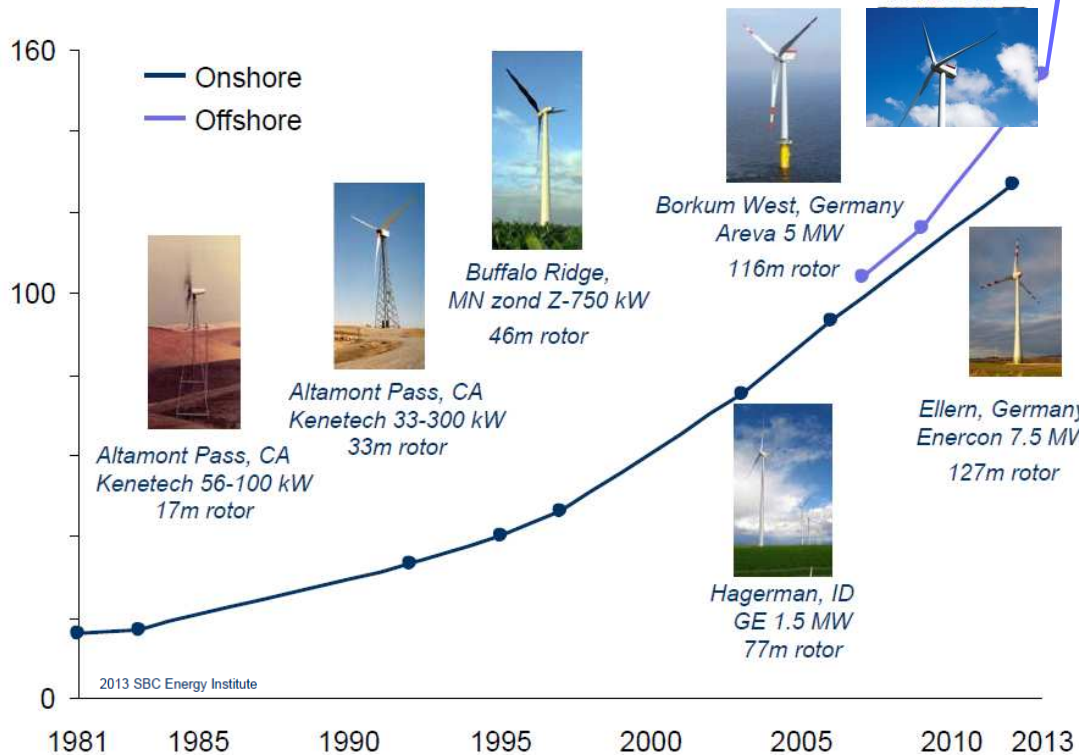


Douglas - Westwood

TURBINES SIZE EVOLUTION

EVOLUTION OF THE TURBINE DIAMETER

Diameter in meters



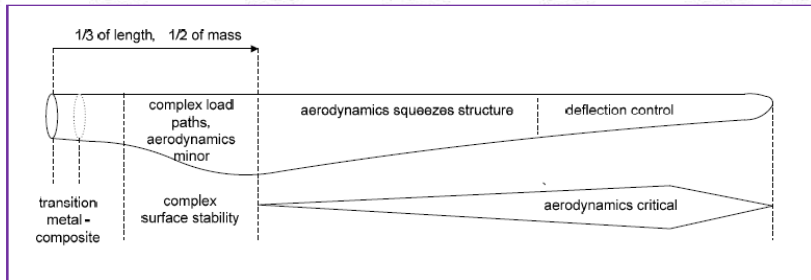
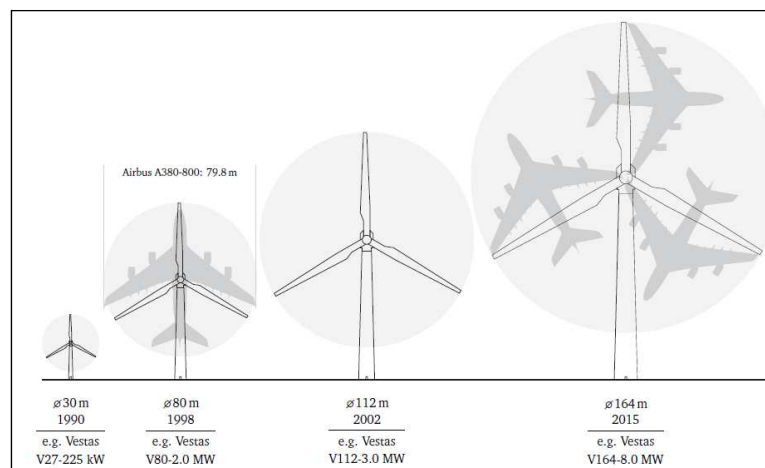
Siemens 1X MW
205m rotor ?

Vestas 8MW
164m rotor

Østerild, Denmark
Siemens 6 MW
154m rotor



Energy Park Five,
Scotland
Samsung 7MW
171m rotor



IPCC (2011), "Special report on renewable energy"



83.5 m SSP Blade for Samsung
S7.0-171 (Denmark)



EUROPEAN OFFSHORE WIND TARGET 2020



NREAP 2020: 43 GW
EWEA estimate
(mid-2014): 23.5 GW
in 2020

Source: BTM Consult- A Part of Navigant



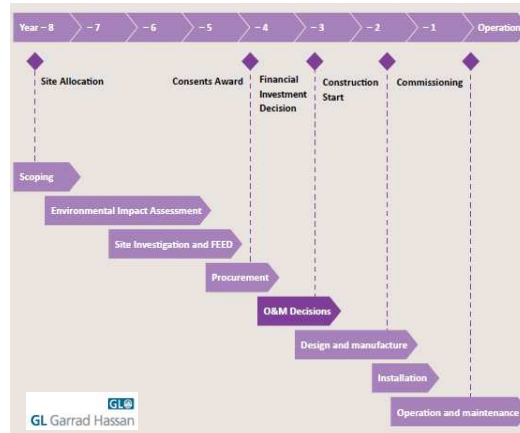
Unit: GW

NREAP: National Renewable Energy Action Plan

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OFFSHORE WIND DEVELOPMENT - MAIN STEPS





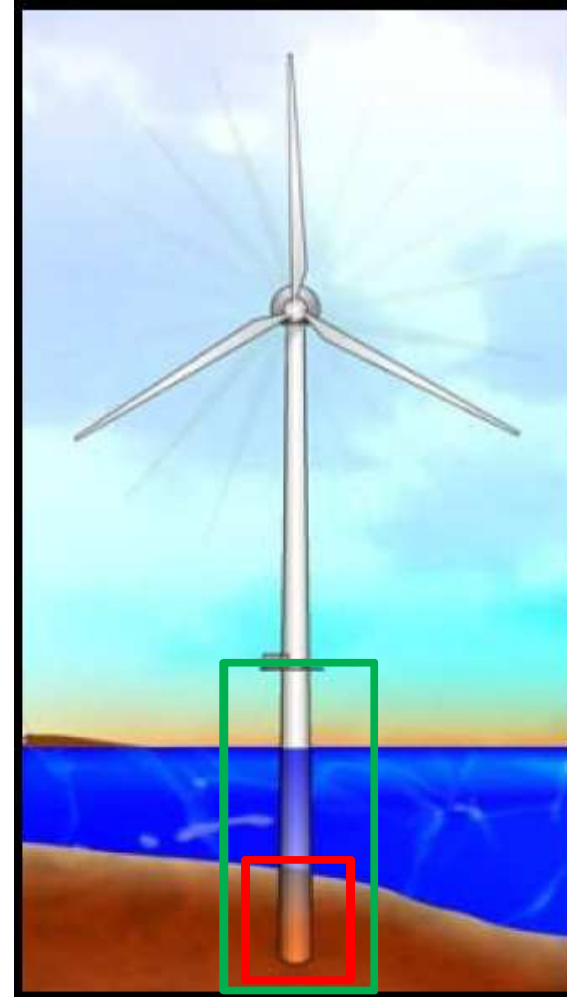
OFFSHORE WIND FOUNDATIONS

BOTTOM FIXED FOUNDATIONS

DEFINITION

- **Civil Engineering definition**
 - Under ground part of the structure
 - Soil-structure boundary
 - Soil mechanics / Geotechnical field
 - Definition used by some french utilities

- **Offshore wind field definition**
 - « Under tower » part of the structure
 - Soil-structure and water-structure boundaries
 - Soil mechanics and Fluid Mechanics
 - Definition generally adopted in UK, Germany and many foreign utilities



OFFSHORE WIND – KEY DATA 2013

The European offshore wind industry
key trends and statistics 2013
January 2014



418
new offshore wind turbines
in 12 wind farms
34% MORE
than in 2012

2,080
turbines are installed
and grid connected

4 MW
average size offshore
wind turbines

work
carried out in: **21** wind farms

new projects:
22 GW
of consented
wind farms



CABLE SUPPLIERS
to offshore wind farms
European market
ENTER ABBOR

39%	27%
Nibkars	JOR
27%	21%
Exxon	TKT
Pyramian	



30 km
average distance to shore

20 m
average
water
depth



6,562 MW
CONNECTED TO THE GRID
IN EUROPE

SUBSTRUCTURES – FOUNDATION TYPES (annual market)

MONOPILE	TRIPOD	JACKET	TRIPILE	GRAVITY
79%	14%	6%	1%	0.2%

**AVERAGE SIZE OF
CONNECTED WIND FARMS**

485 MW
78% more than
in 2012



Wind turbine
MANUFACTURERS

74%	12%	10%	4%	0.2%	0.2%
Siemens	Bard	Vestas	Servicon (Repower)	Alstom	Gamesa

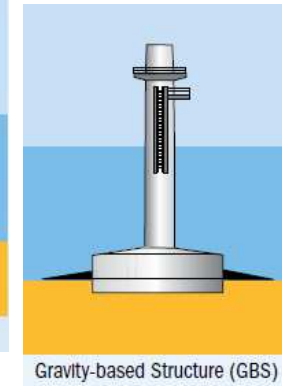
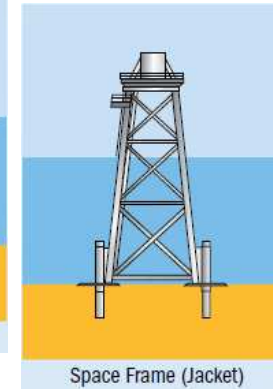
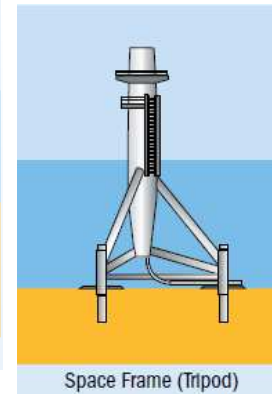
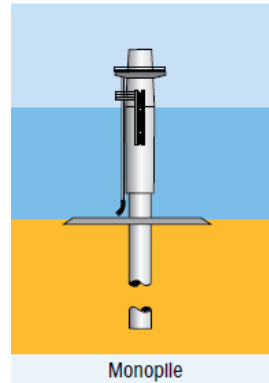
DEVELOPERS

48%
DONG

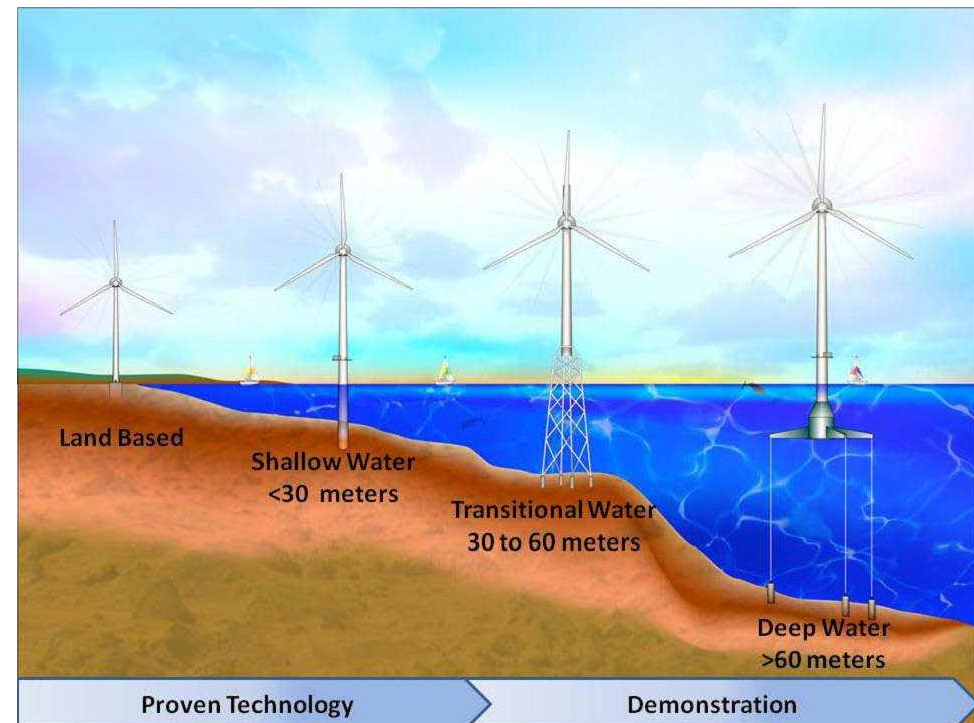
BOTTOM FIXED FOUNDATION

TYPE OF FOUNDATIONS

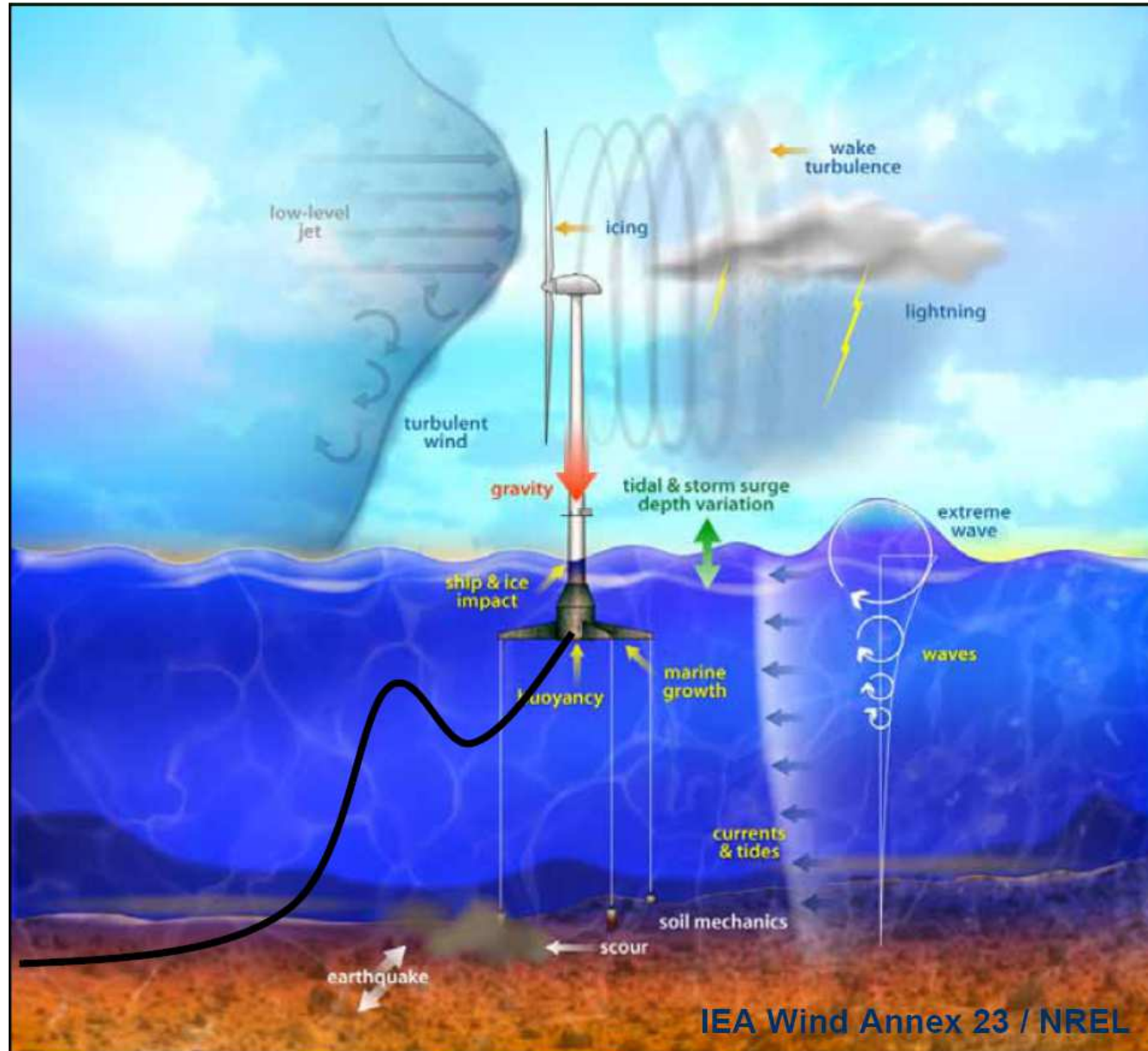
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 - Monopile
 - Tripod
 - Jacket
 - Gravity Based Foundation (GBF or GBS)



- Usually, the choice of the structure depends on the water depth and the sea bed (rock, sand...)
 - Monopile typically until 20/30m
 - Tripod typically until 30/40m
 - Jacket typically until 50/60m
 - GBS typically until 30/50m

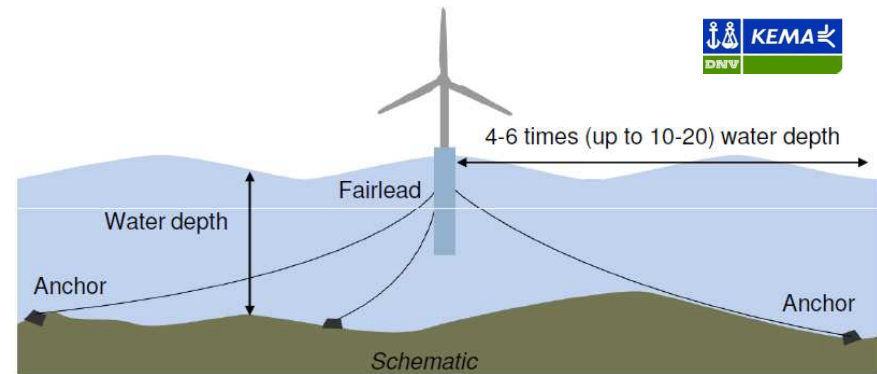


FLOATING FOUNDATIONS



SPAR: HYWIND (2009)

- 800 ml mooring lines
- Turbine Siemens SWT 2.3MW
- Water depth: 220 m



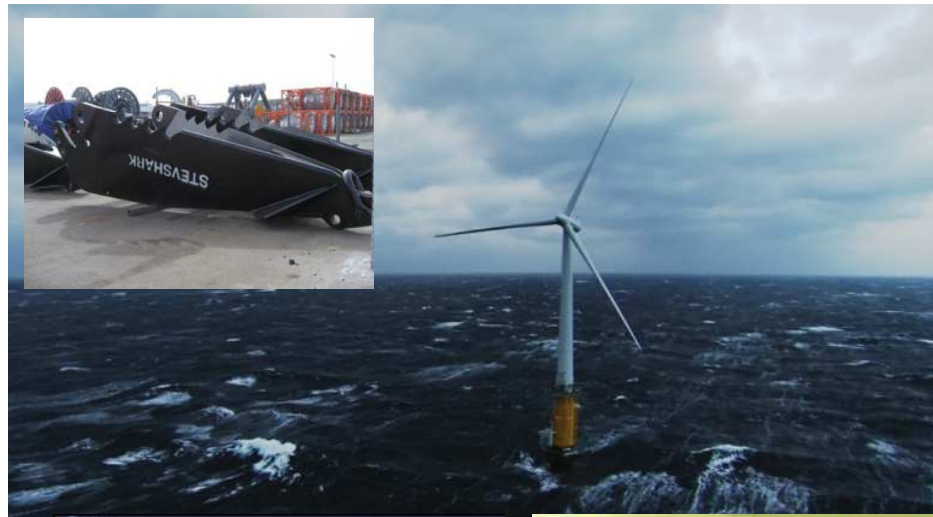
Hywind Demo – in operation since 2009

Main Data

- Wind turbine: 2.3 MW
- Turbine weight: 138 tonnes
- Draft: 100 m
- Displacement: 5300 m³
- Diameter at water line: 6 m
- Water depths: 120-700 metres

Characteristics

- Full scale demo
- Based on a slender buoy concept
- Steel tower and substructure
- Dynamic pitch regulation
- Assembled at inshore site in sheltered waters
- Towed upright to field
- Designed for extreme North Sea conditions



ANALYSIS TOOLS

- Simo-Riflex-Hawc2 (Marintek / Risø)
- Hawc2 Offshore (Risø)
- Bhawc (Siemens Wind Power)
- Flex5 (Stig Øye / StatOil)
- Simo-Riflex-TDHMill (Marintek / StatOil)

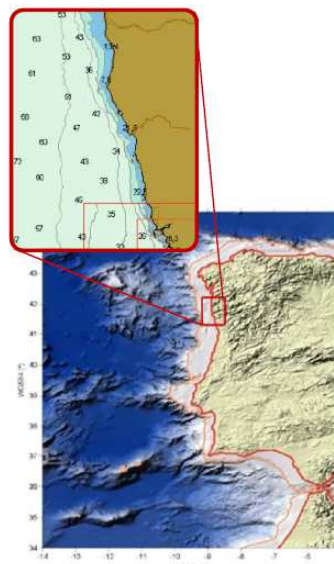
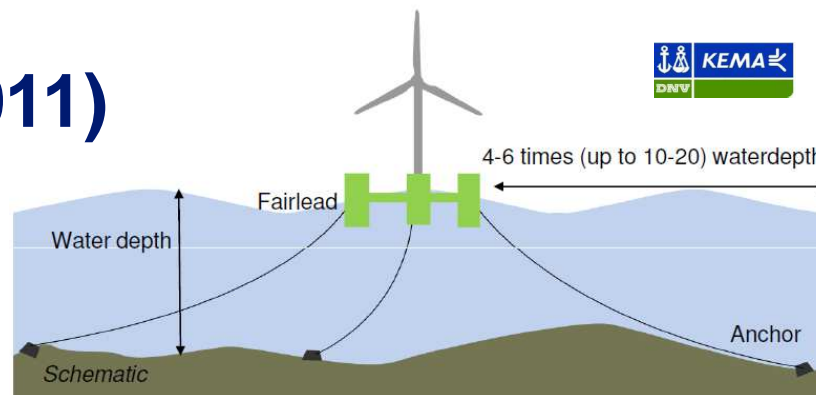
DYNAMIC CHALLENGES



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SEMI-SUB : WINDFLOAT (2011)



Phase 1 – Demonstration

Capacity: 2MW WindFloat prototype
Location: Aguçadoura, grid connected
 ~6 km of coast, 40 - 50 m water depth
Turbine: 2MW offshore wind turbine
Test period: 24+ months

Phase 2 - Pre-commercial

Capacity: ~27MW (~5 WindFloat units)
Location: Portuguese Pilot Zone
Turbine: Likely Vestas and other, Multi MW



Core focus of DemoWindfloat

Core focus of NER300



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JAPANESE PROJECTS : SEMI-SUB AND SPAR (2013)

Fukushima
(Mitsui/Hitachi)



Fukushima

- Design for use with a 2MW turbine
- Width 58 m
- Total column length 32 m of which 16 m will be submerged
- Hub height 60 m

GOTO OWT
(Toda/Hitachi)



Full Scale:

- 2MW downwind turbine with 80m rotor diameter
- Total spar length 172m
- Total weight incl. Turbine 3,400 t
- Steel with pre-stressed concrete
- Steel chain mooring, 3 points, catenary, attached to drag anchors

Image Source: Kyoto University

5

JAPANESE PROJECTS : SEA ANGEL (2015)

Fukushima
7 MW (MHI)

=

Biggest Offshore Wind turbine installed



Items	Scopes
Turbine	<ul style="list-style-type: none"> • Verification of 7MW hydraulic turbine.
Floating	<ul style="list-style-type: none"> • Development of V-shape semi-sub floating. • Development of the reduction of floating motion by turbine control and O&M program.
Mooring	<ul style="list-style-type: none"> • 8 pieces catenary.



- Rotor diameter 164m
- Hub height 105m (ASL)
- Height of the floater 32m

Installed
summer 2015

FUKUSHIMA-FORWARD
Project



ADVANCED SPAR 5 MW (2016)

- Last part of Fukushima forward project
 - 5MW Turbine
 - Hitachi
 - Downwind type
 - Advanced-spar concept
 - Japan Marine United
 - Low draft solution (30m)
 - Large sections (50m)

➔ Japan is still working on prototypes



The floater lost control and leaned on 9 May

The floater recovered stability again on 14 May

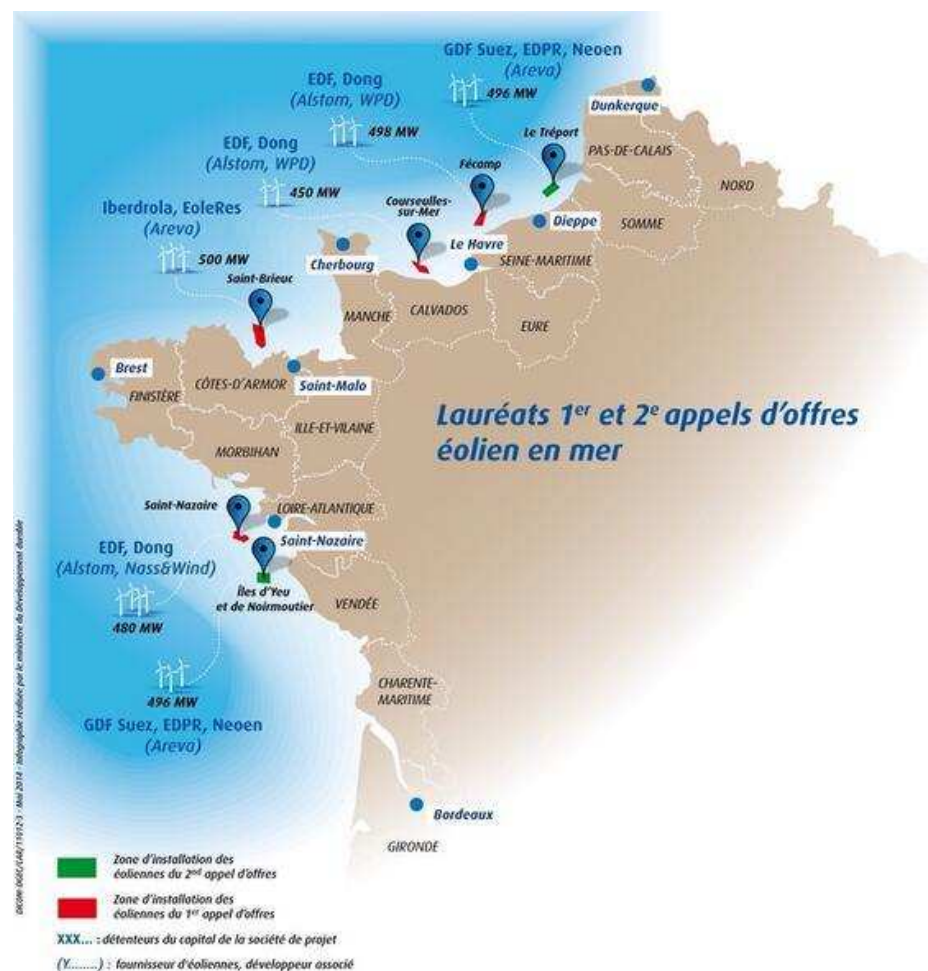


OFFSHORE WIND IN FRANCE

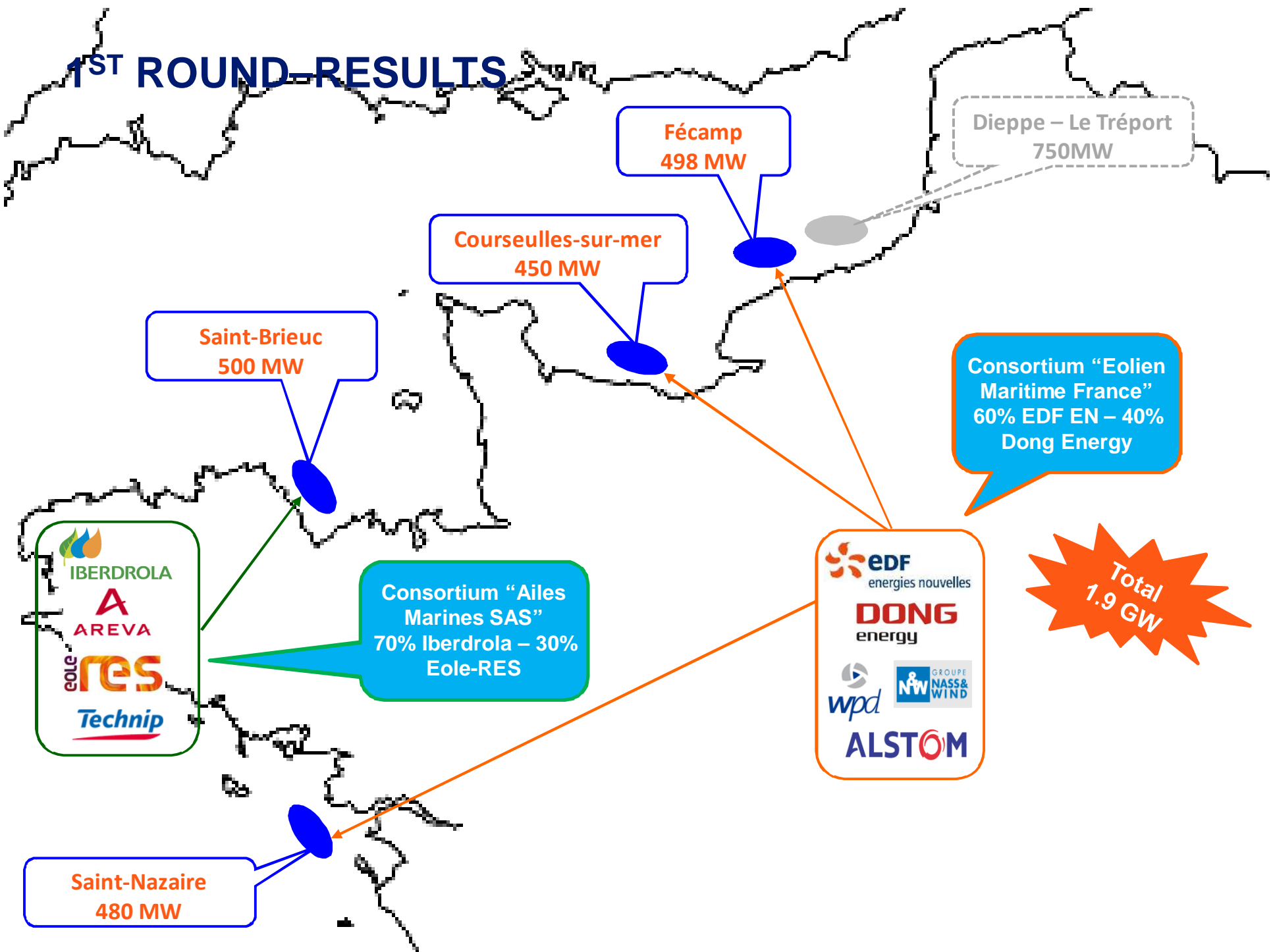


FRANCE

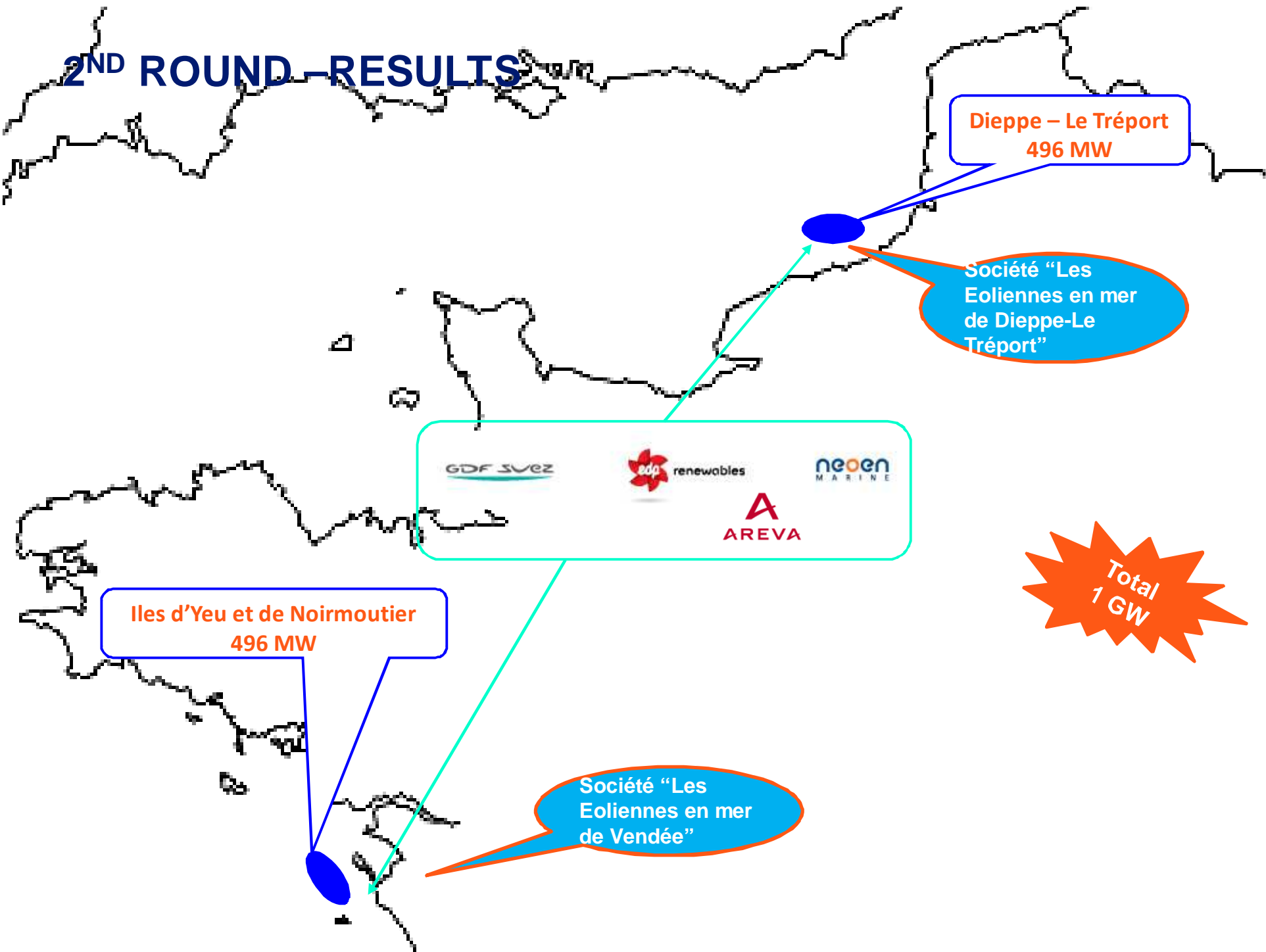
- 2004 : 1st Call for Tender “Centrales Eoliennes en mer”. 1 site awarded: Côte d’Albâtre (Velettes – Enertrag 105 MW with Areva). NIMBY issues... Cancelled.
- 2011 : 1st Round (Call for Tender) - 3 GW - 5 sites (Le Tréport - **Fécamp - Courseulles - St Brieuc et St Nazaire**). 4 sites awarded **1.9 GW**. Construction: 2019-2020.
- 2013 : 2nd Round - 1 GW - 2 sites (**Le Tréport et Iles d’Yeu & de Noirmoutier**). Construction : 2021-2023.



1ST ROUND - RESULTS



2ND ROUND - RESULTS



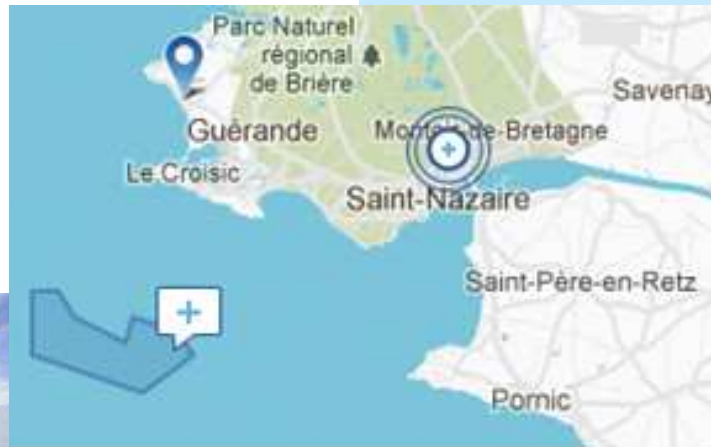
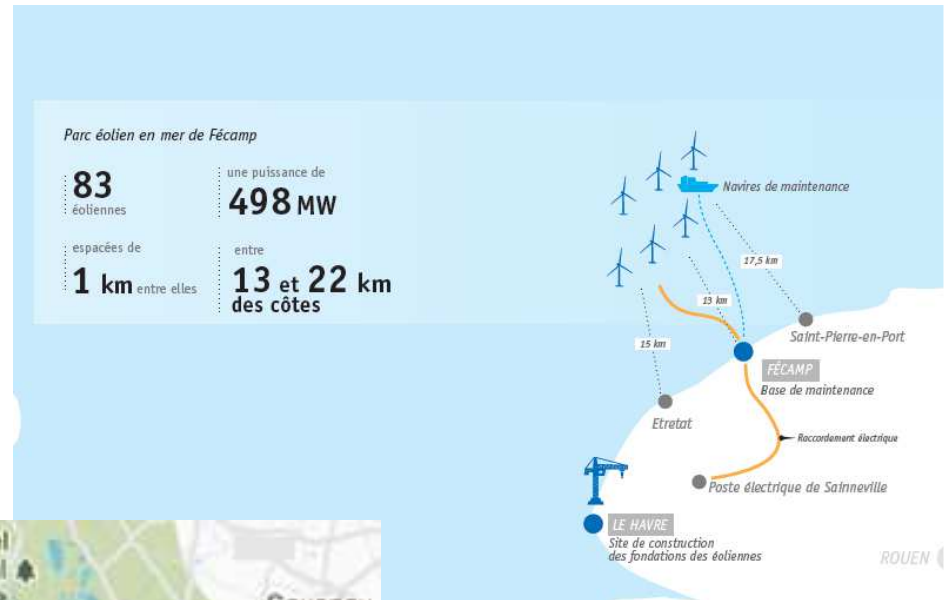
INDUSTRIAL SIZE PROJECTS

- **Ambition : 3 GW of Offshore Wind by 2020**

- 6 sites on the Atlantic coast
- Water depth : 20m-40m
- Distance to shore : 10/20 km

- **Large wind farms**

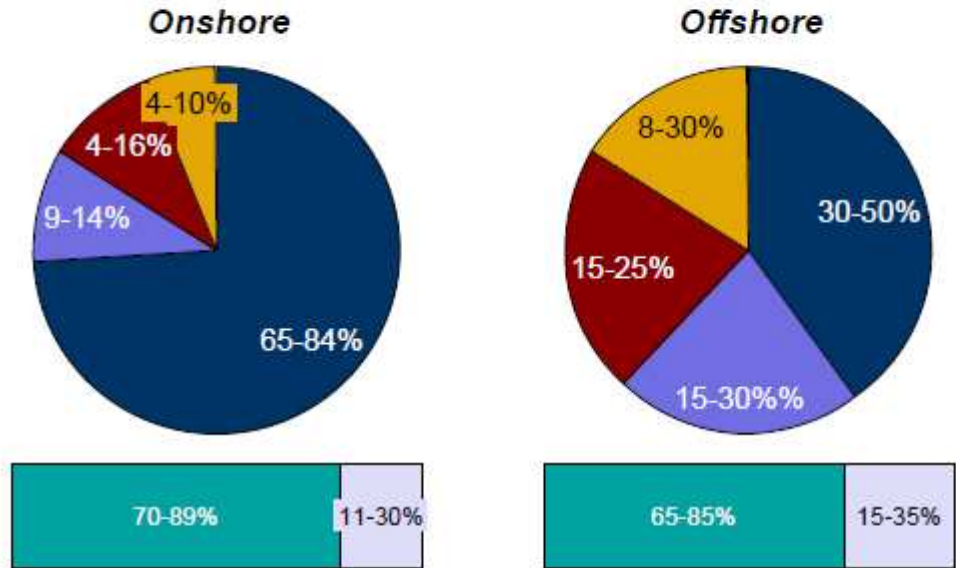
- Typical installed power : 500 MW
- Turbine : 5MW to 8 MW
 - Diameter ~ 150 m
- 70 to 100 turbines / farm



COÛT DE L'ÉLECTRICITÉ

Réduire le coût de l'électricité

TYPICAL ONSHORE & OFFSHORE WIND COST BREAKDOWN
Capital cost breakdown (top) & share of capital in levelized cost of electricity (bottom)



- Wind turbine
- Construction (inc. Foundation)
- Capital Cost
- Grid connection
- Planning & miscellaneous
- Operation & Maintenance Cost

CAPEX = Capital Expenditure

OPEX = Operational Expenditure

CoE = Cost of Electricity

$$CoE = \frac{CAPEX + OPEX}{PRODUCTION}$$

Réduire le coût de l'électricité pour être compétitif lorsque les subventions étatiques s'arrêteront

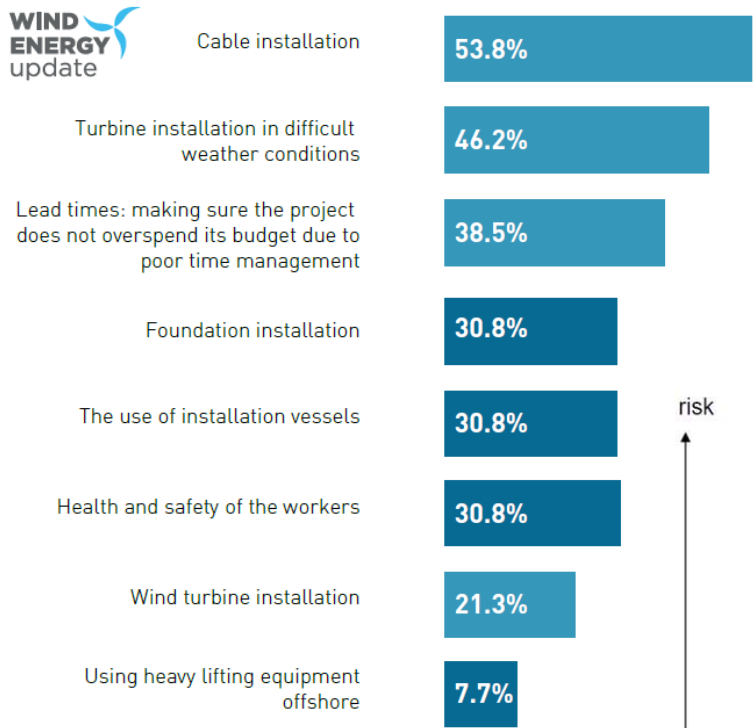
Un enjeu majeur!



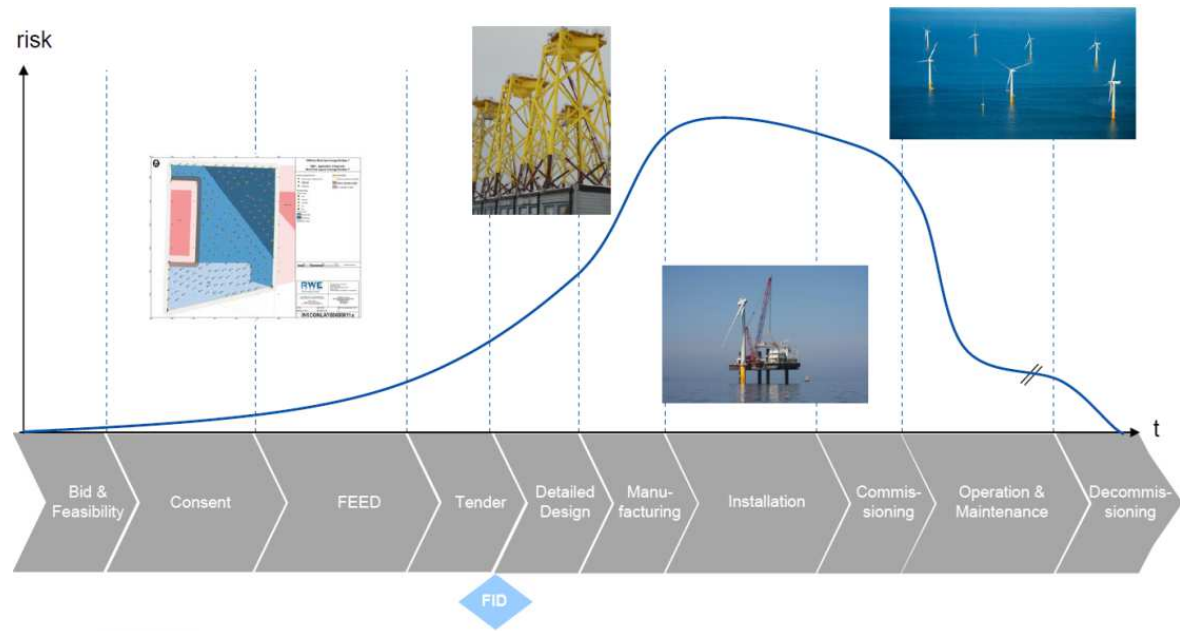
PRINCIPAUX RISQUES LIES A LA CONSTRUCTION

Lever les risques

Résultat du sondage (2012-2013) sur les principaux risques en phase construction, vus par les développeurs de projets en Europe (*Utilities*) :



Cable installation remains the top challenge for the majority of Europe's largest utilities. The cost of cable repair and the complexity of the cable installation procedure (especially in deeper water, further from the shore) could be the reason for this fact.



■ Vision RWE :



FRENCH FLOATING PROJECTS

ADEME "AAP" : APRIL 2016

4 sites selected on the French coasts for precommercial farms
20/30 MW by project (3-6 turbines)
Consortiums (Turbine/Floater/Utility)



1 Atlantic site



3 Mediterranean sites



2 PROJECTS ALREADY AWARDED

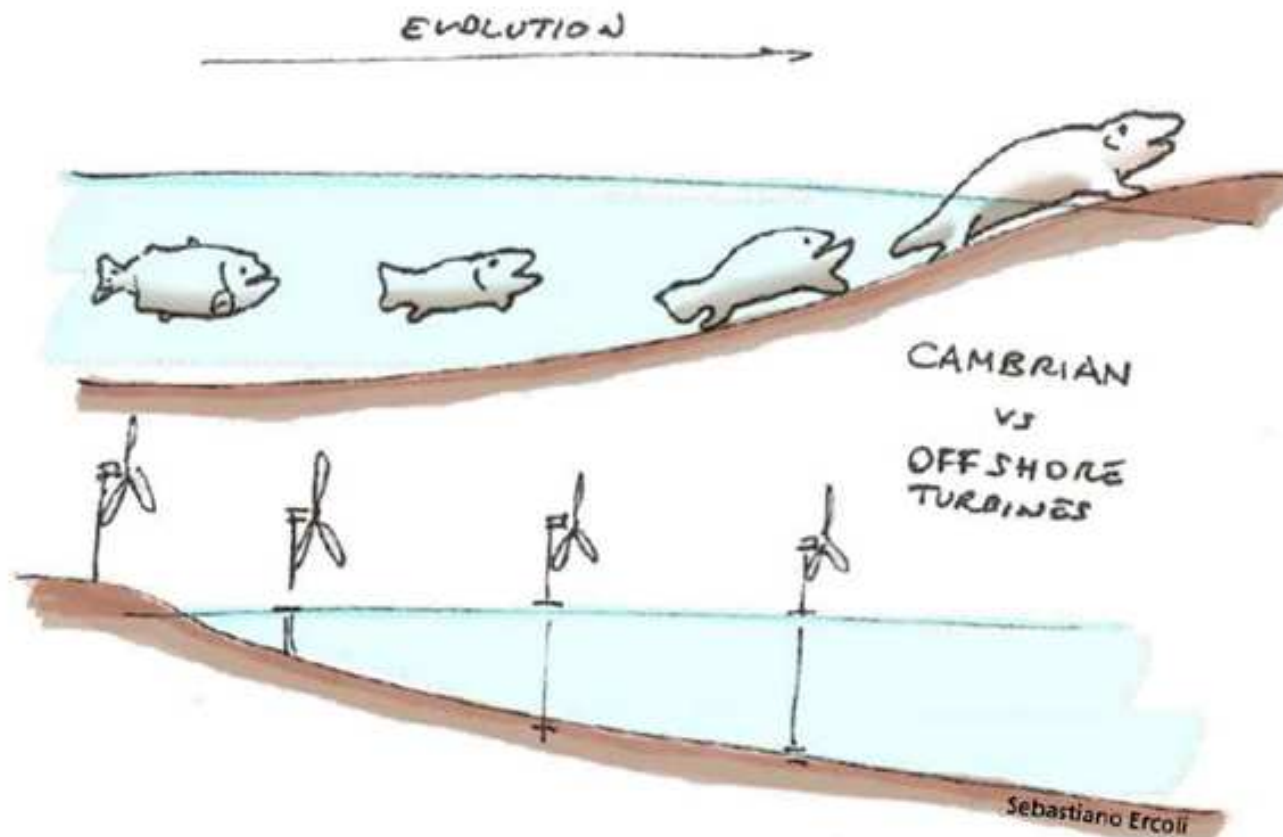
- Ile de Groix (Atlantic) – 24 MW
 - EOLFI
 - General Electric (ex-Alstom) / 6MW turbine
 - DCNS
- Gruissan (Languedoc) – 24 MW
 - Quadran
 - Senvion / 6 MW turbine
 - IDEOL
- Demonstrator project
 - IDEOL 2MW
 - Under construction by Bouygues TP
 - SEMREV 2017



Will be the first Offshore Wind turbine in France !



BOTTOM FIXED / FLOATING FOUNDATIONS

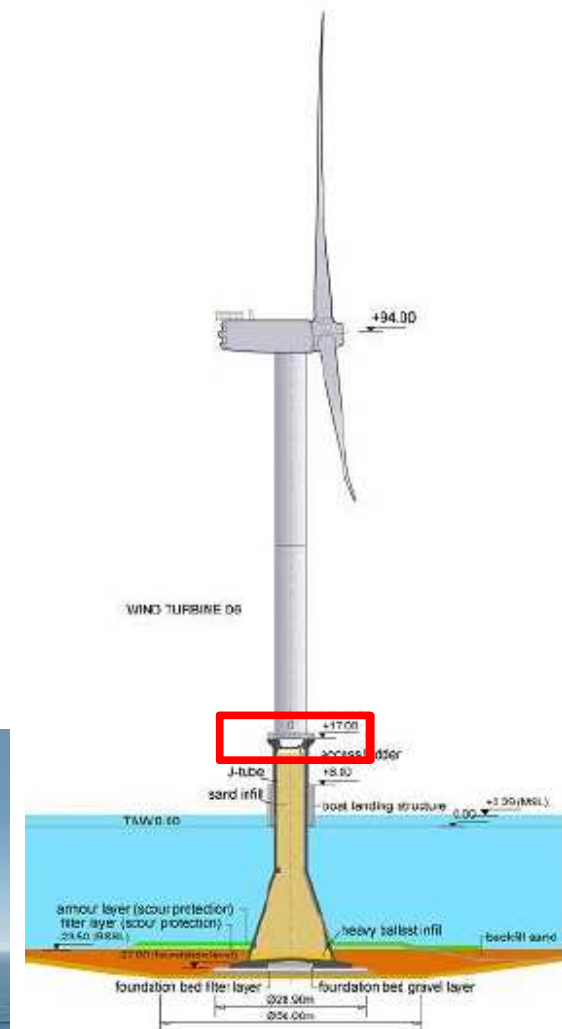


BOTTOM FIXED FOUNDATIONS



BOTTOM FIXED FOUNDATION DESIGN METHODOLOGY

- **Aerodynamic forces**
 - Coming from the turbine
 - Provided by the turbine manufacturer
- **Hydrodynamic forces**
 - Current
 - Waves
- **Soil response**
 - Depending on the sea bed type
 - Depending on the foundation type
- **Transition piece**
 - Link between sub-structure and Turbine/Mast system
 - Boundary between hydrodynamic design and aerodynamic design

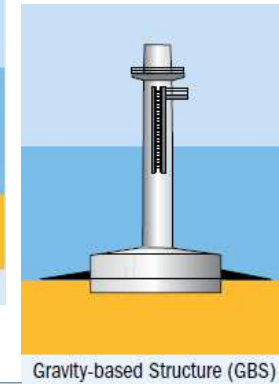
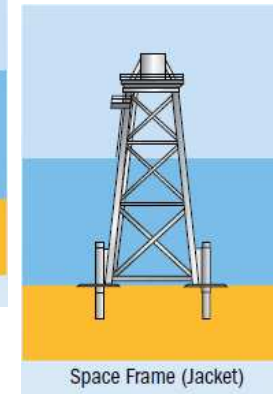
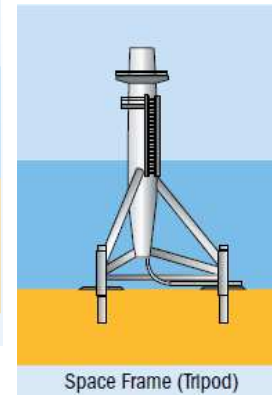
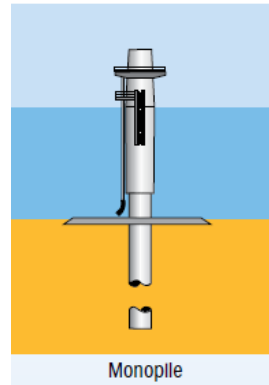


BOTTOM FIXED FOUNDATION

TYPE OF FOUNDATIONS 1/3

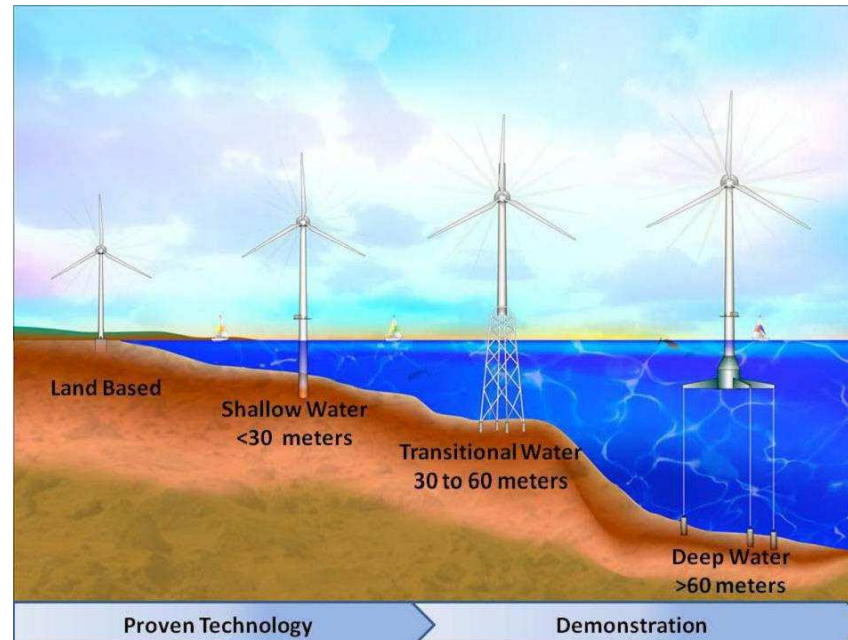
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- Jacket
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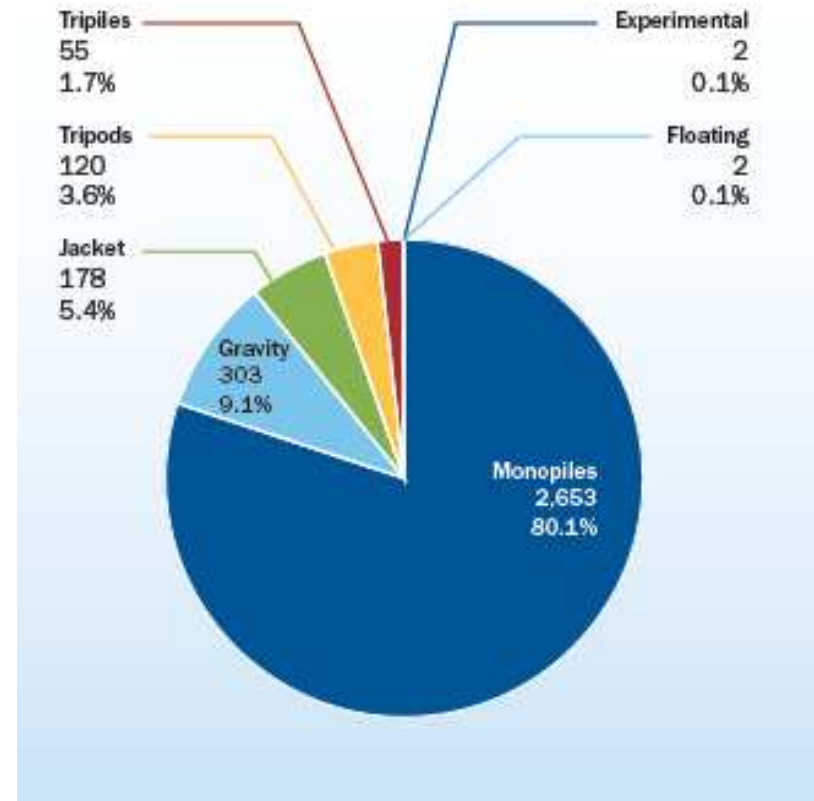
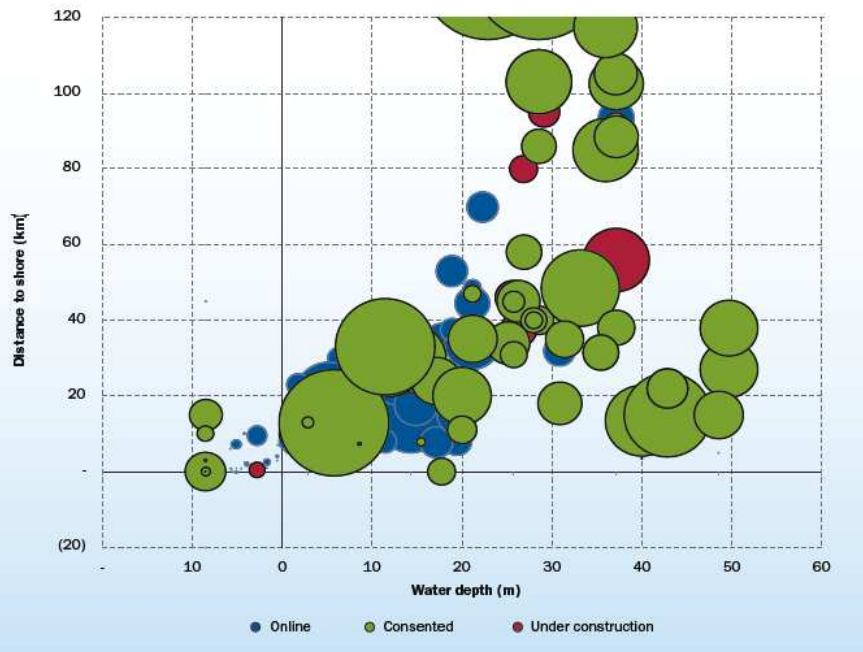
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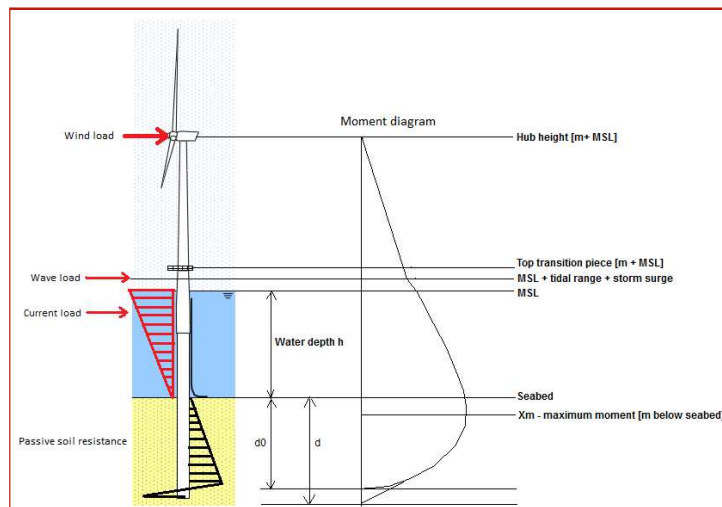
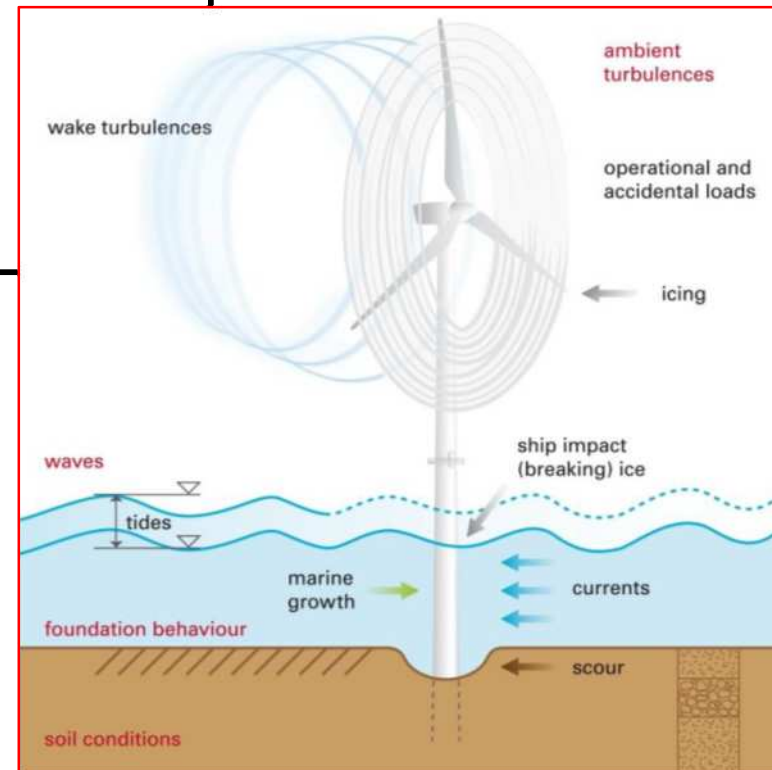
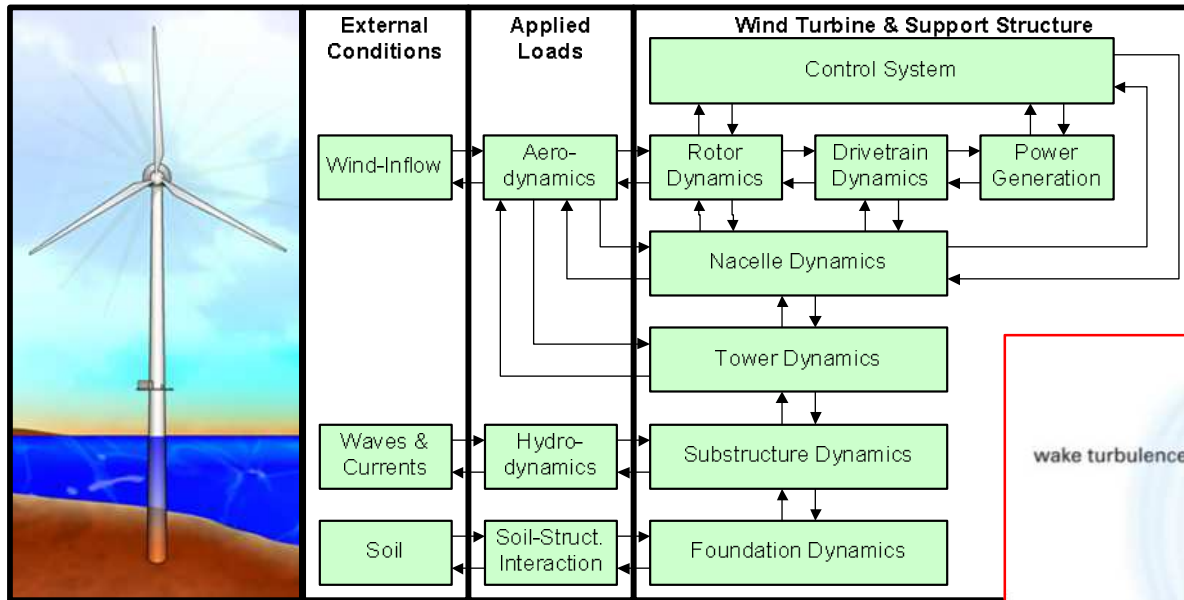
BOTTOM FIXED FOUNDATION

TYPE OF FOUNDATIONS 2/3

- **Repartition of OWT foundations**
 - End 2012 figures
 - Monopile is the most used foundation type
 - Denmark
 - Germany
 - UK
 - GBF is significant
 - Tripod/Tripile is not common



COMPLEX DESIGN...



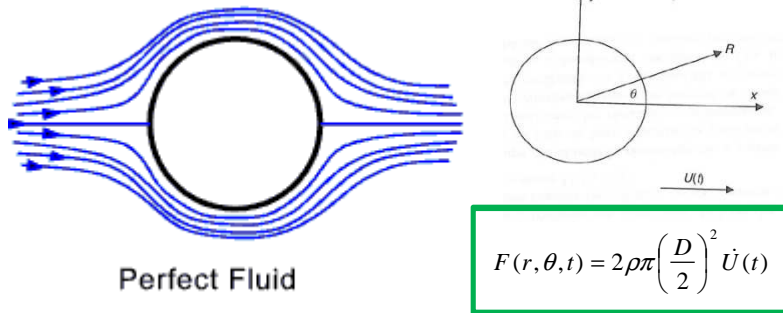
BOTTOM FIXED FOUNDATION

HYDRODYNAMIC MODELS - FORCES

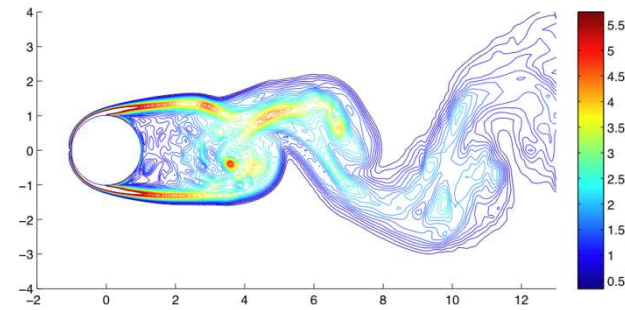
- Hydrodynamic loads model - Standards
 - Semi-Empirical approach (Morison formula)
 - Thin bodies approximation


$$F = C_M \cdot \rho \pi \frac{D^2}{4} \dot{U}(t) + \frac{1}{2} \rho \cdot C_D \cdot D \cdot U \cdot |U|$$

Perfect fluid approx.



Viscous effect



Coefficients + **Kinematics**  **Hydrodynamic Force**

BASIN TESTS

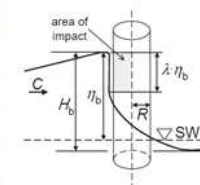
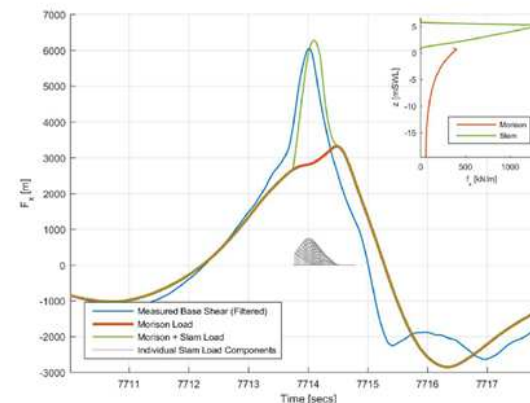
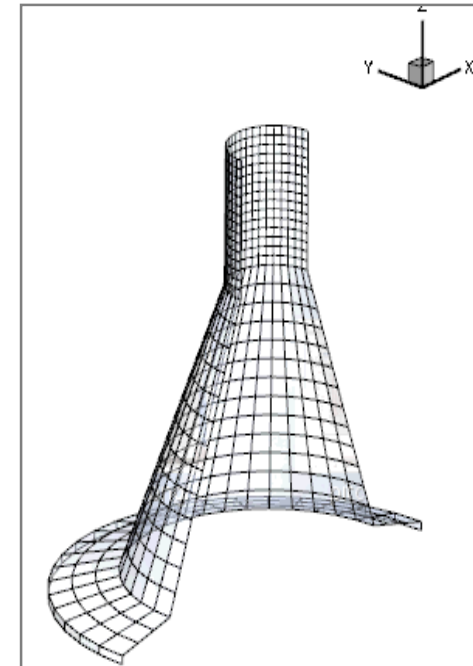
HYDRODYNAMIC FORCES EVALUATION – MODEL CALIBRATION

- **Froude scaling**

- Inertia forces conserved
- Reynolds similitude lost
- State of the art of the O&G industry

- **Typical scale**

- Between 1/20th and 1/50th
- Water depth : 40m => 1m to 2m
- Structure diameter : 7m => 15 to 40 cm
- ECN, Oceanide, IFREMER...

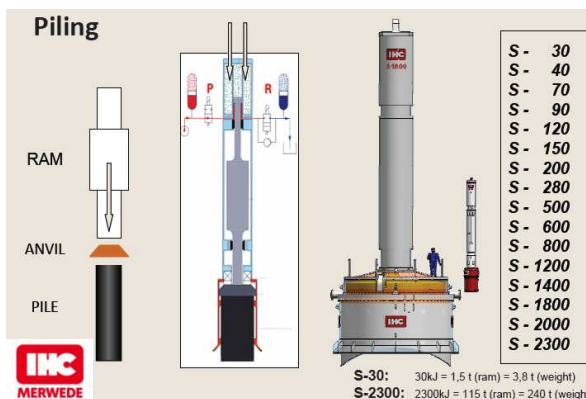
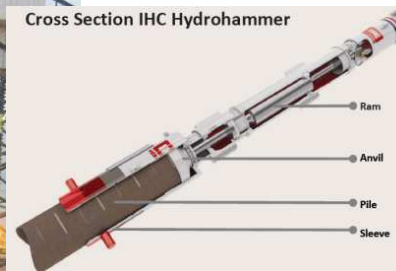
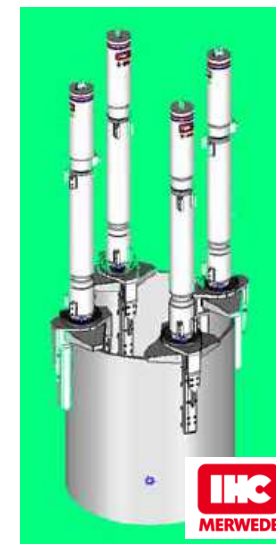


MONOPILE INSTALLATION L

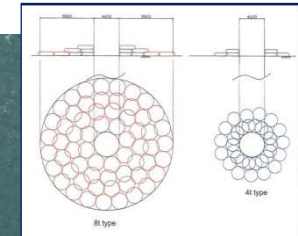
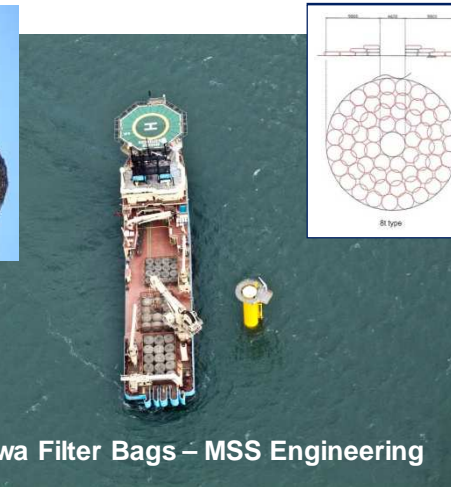
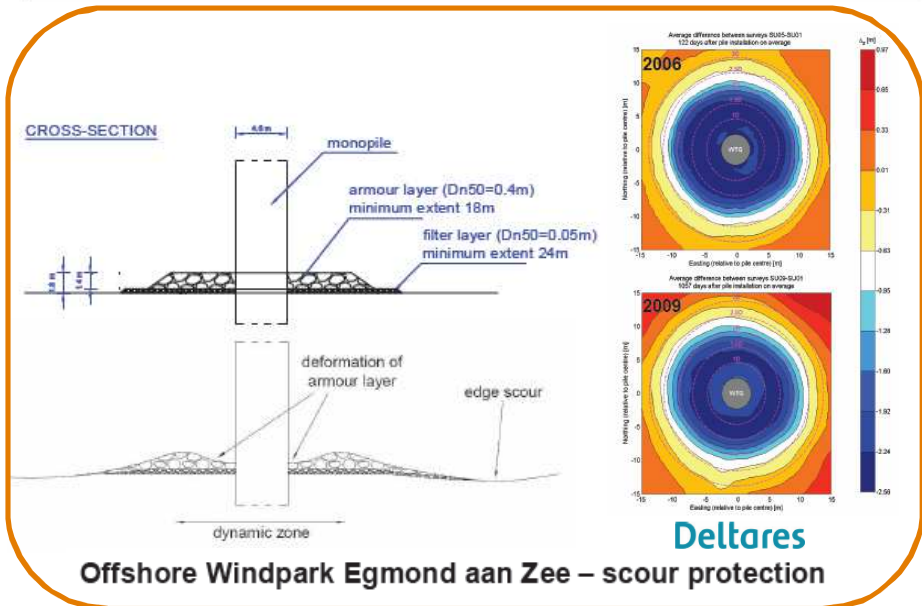
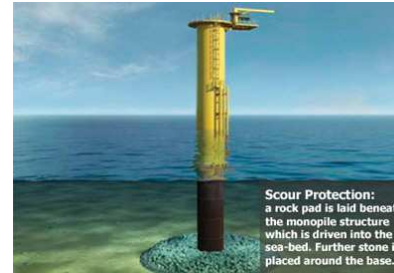
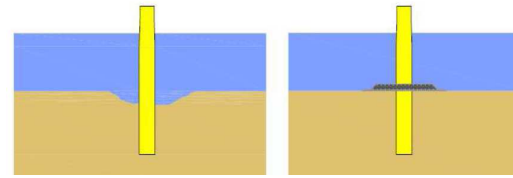
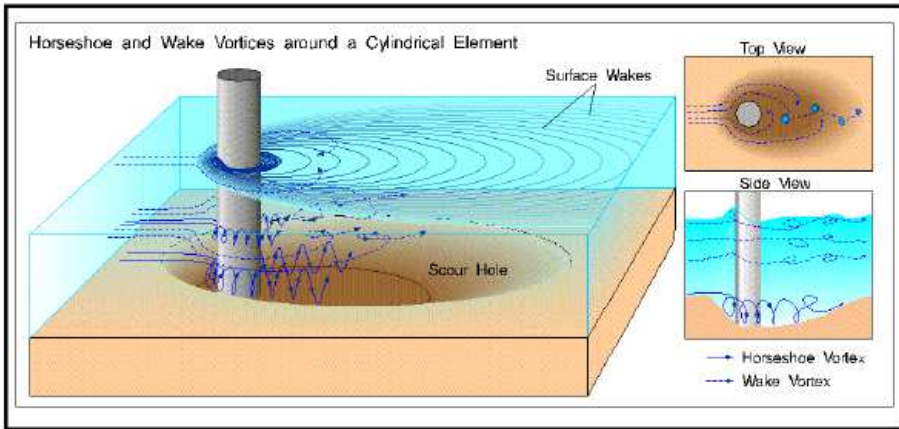


MONOPILE PILING

- Hydro-hammer or vibro-driving devices are used.
- Noise impact on sea mammals: key issue!
- Multi-Hammer are used when diameter > 7.5 m



SCOUR PROTECTION



Teesside – Kyowa Filter Bags – MSS Engineering



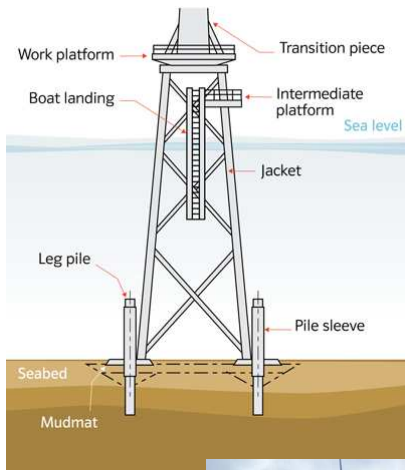
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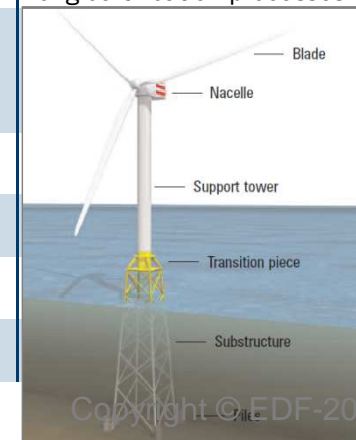
JACKET



- Jacket : steel lattice structure (welded pipes \varnothing 0.5 – 1.5m) from Oil & Gas industry. ~ 1000tons (> 1km welding!).
- Structure suitable for deep water (< 50-60 m) with heavy turbines (> 5 MW). Small leg monopiles are driven in the seabed (\varnothing 1 – 2.5m).
- 1st offshore wind installation: demonstration site Beatrice in Scotland in 2006 (2 x REpower 5 MW – 45 m water depth).



Advantages	Disadvantages
Lightweight and stiff structure	Complexity of fabrication
Better global load transmission compared to monopiles	Large number of joints required compared to other latticed structures
Large variations in water depth can be covered through cantilevering piles or modifying the geometry	Logistical issues due to the templates (pre-piling case)
No scour protection required	Complex connection to transition pieces
Structural redundancy	High manufacturing lead-times
Low soil dependency	No standardized design that leads to long certification processes
Good response to wave loads. Little sensitivity to large waves and limited dynamic amplifications of loads due to high stiffness	
Limited storage area compared to GBF	
Faster fabrication compared to GBFs (serial production)	
Better quality control	
Easy decommissioning	



TRIPOD INSTALLATION (ALPHA VENTUS)



Tripods being welded



Tripod up-ended for shipping



Tripods arriving at Wilhelmshaven port



Heavy-lift crane ship on site






Tripod foundation lowered to seabed



Installation complete

VARIOUS GBS CONCEPTS

Type	Features	Example
Self-Buoyant ("Floating")	GBS can be floated out and towed to the offshore site using standard tugs. At the site, GBS is filled with ballast.	 <p>Gravitas</p>
Auxiliary Buoyancy ("Semi-floating")	Special transport vessel required for buoyancy support. This concept helps reduce concrete volume. Additional ballasting at site.	<p>Strabag</p> 
Crane Lowered	GBS cannot float. A heavy lift crane vessel is required. A large transportation barge + heavy crane vessel can also be used. Possible additional ballasting at site.	 <p>Rambiz-DEME</p>

TURBINE INSTALLATION



TURBINE INSTALLATION



TURBINE INSTALLATION



INSTALLATION – HEAVY OFFSHORE VESSELS

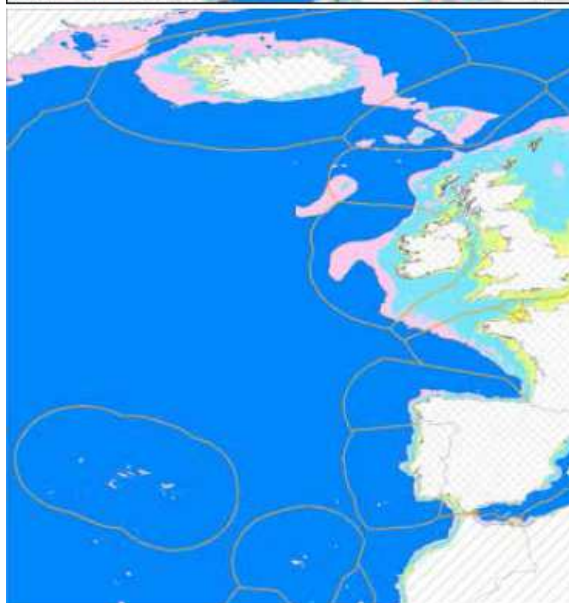
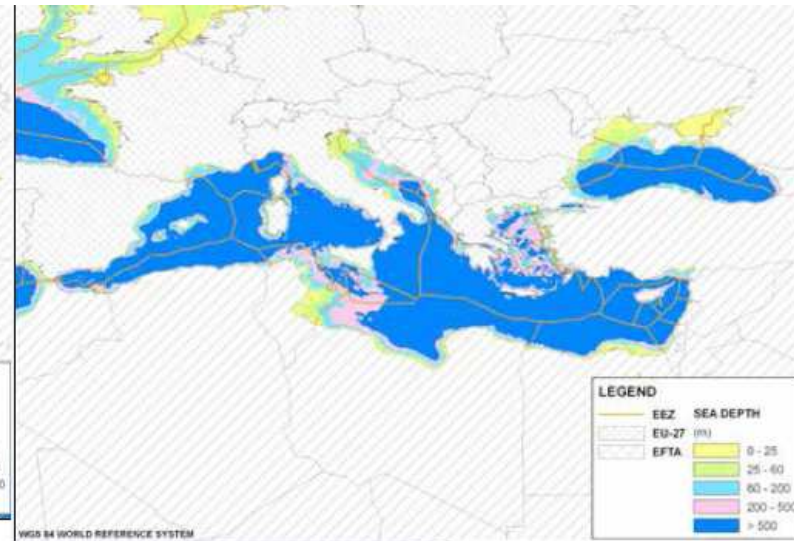
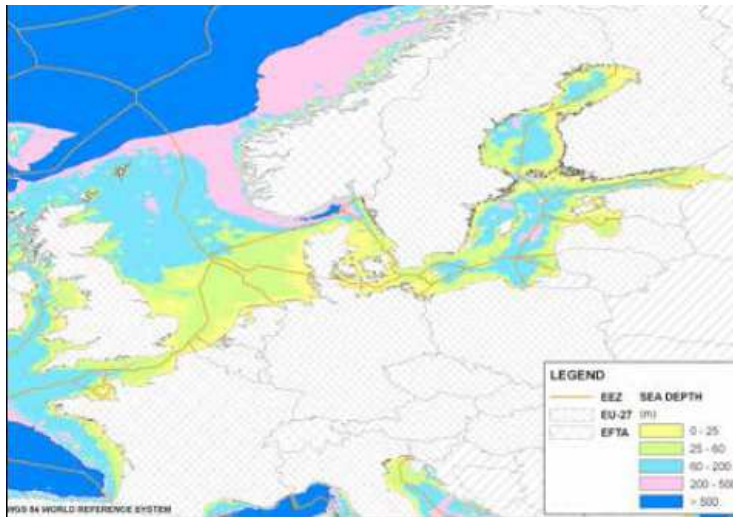


FLOATING FOUNDATIONS TECHNOLOGIES



FLOATING FOUNDATION

WHY?



 0-60m : Bottom Fixed Foundations

 60-500m Too deep for Fixed
→ Floating

 >500m → Floating ?

FLOATING FOUNDATION

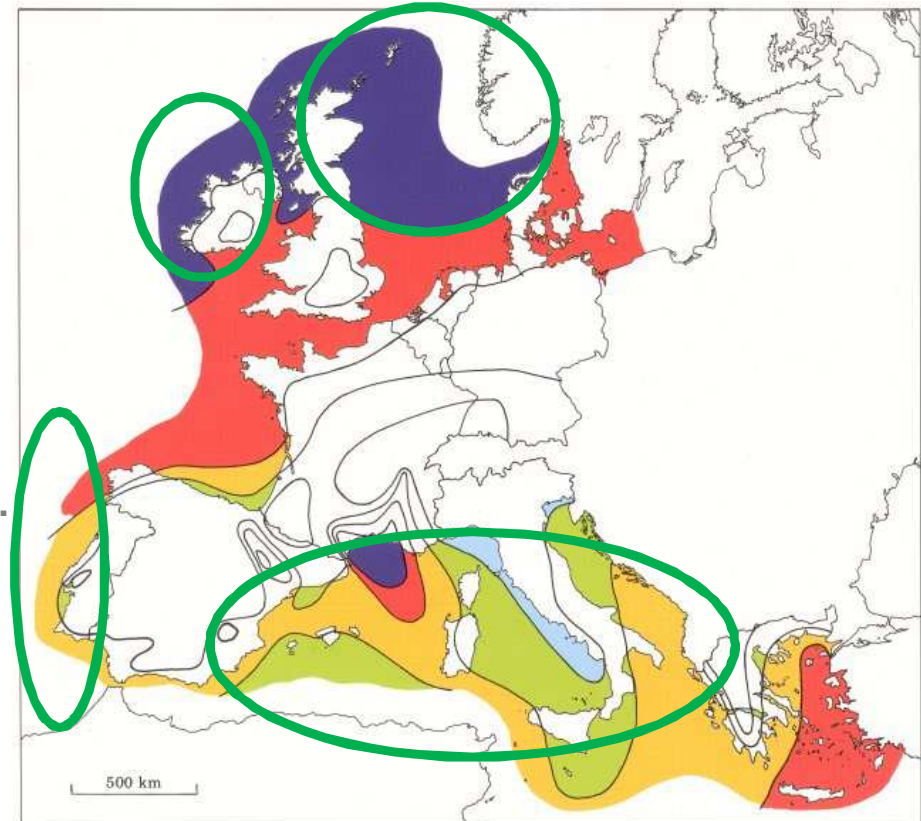
WHY ?

- **Going to deeper waters**
 - Bottom fixed foundation : maximum ~ 50-60 m water depth (structure size, installation vessel: crane, Jack Up...).

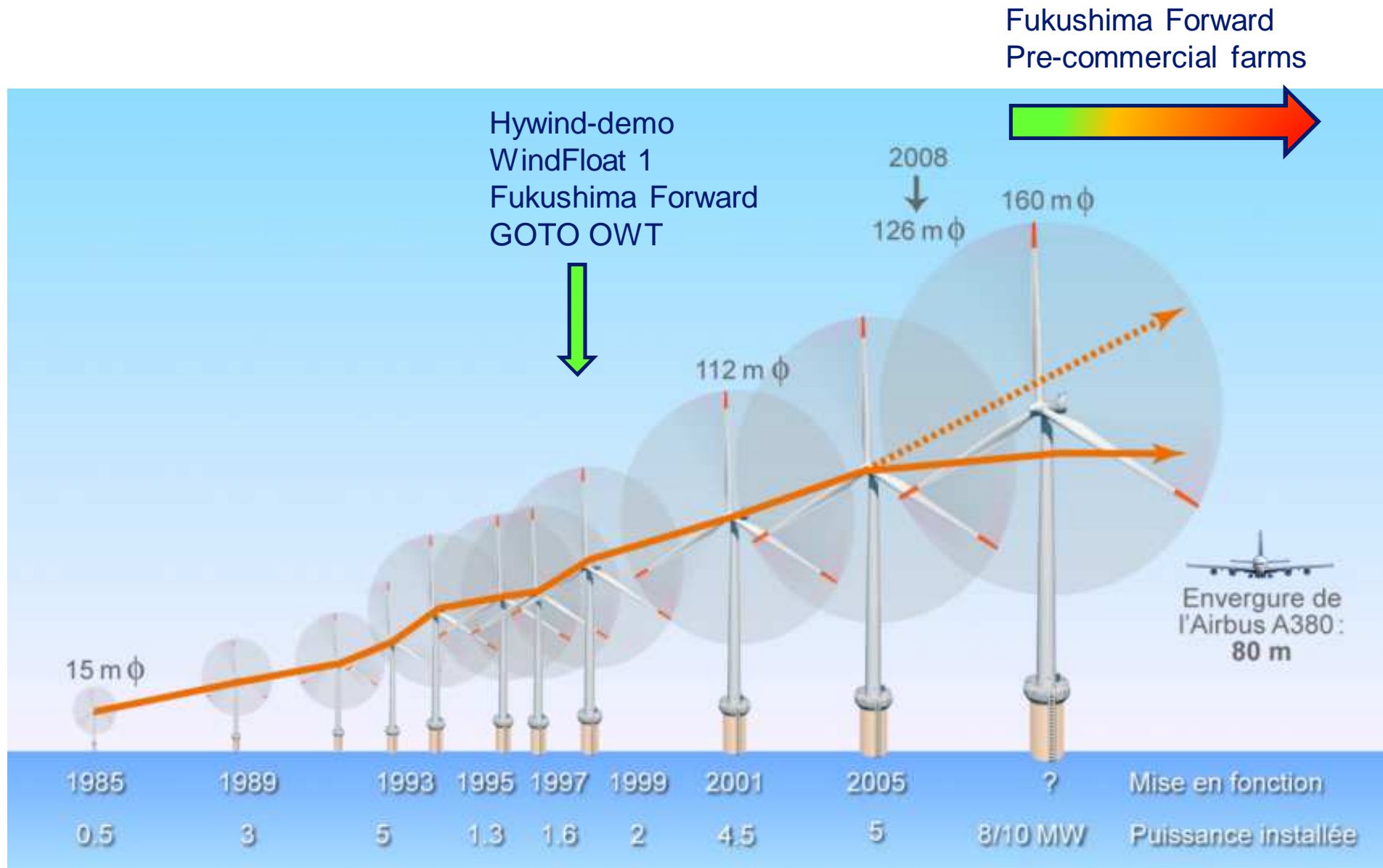
- **European Areas**
 - Offshore Norway, Scotland, Ireland
 - Mediteranean Sea
- **Technology from Oil & Gas offshore.**

- **Installation should require less specific vessels**
- **Possibility to assemble both turbine and platform onshore (port) and tow them out on site.**

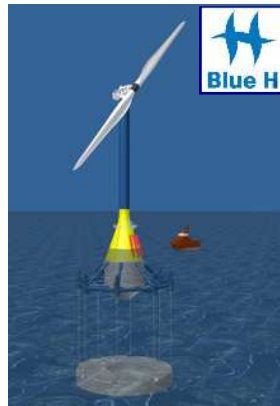
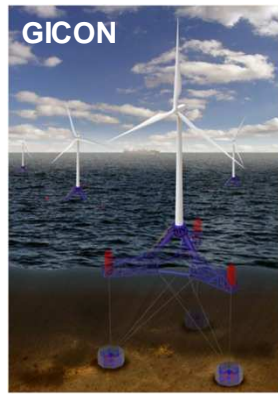
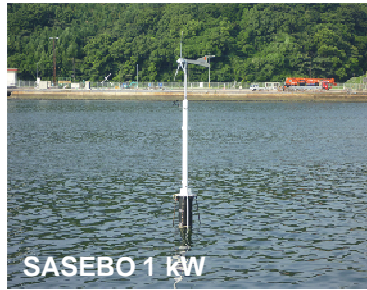
- **Challenges**
 - Platform motions
 - Moorings
 - Dynamic electric cable
 - Further from shore means higher winds but also higher sea states



Wind resources over open sea (more than 10 km offshore) for five standard heights									
10 m		25 m		50 m		100 m		200 m	
$m s^{-1}$	Wm^{-2}	$m s^{-1}$	Wm^{-2}	$m s^{-1}$	Wm^{-2}	$m s^{-1}$	Wm^{-2}	$m s^{-1}$	Wm^{-2}
> 8.0	> 600	> 8.5	> 700	> 9.0	> 800	> 10.0	> 1100	> 11.0	> 1500
7.0-8.0	350-600	7.5-8.5	450-700	8.0-9.0	600-800	8.5-10.0	650-1100	9.5-11.0	900-1500
6.0-7.0	250-300	6.5-7.5	300-450	7.0-8.0	400-600	7.5- 8.5	450- 650	8.0- 9.5	600- 900
4.5-6.0	100-250	5.0-6.5	150-300	5.5-7.0	200-400	6.0- 7.5	250- 450	6.5- 8.0	300- 600
< 4.5	< 100	< 5.0	< 150	< 5.5	< 200	< 6.0	< 250	< 6.5	< 300



EXAMPLES OF FLOATING PROJECTS...

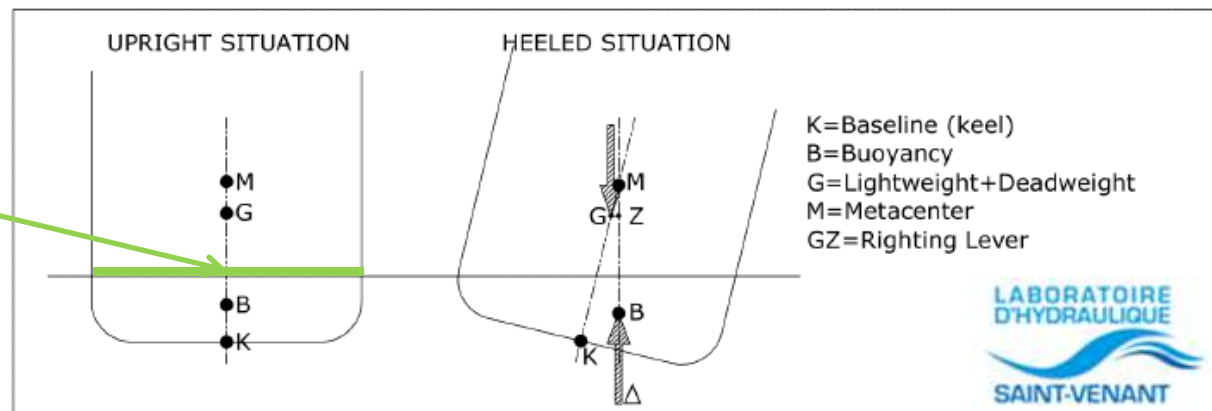
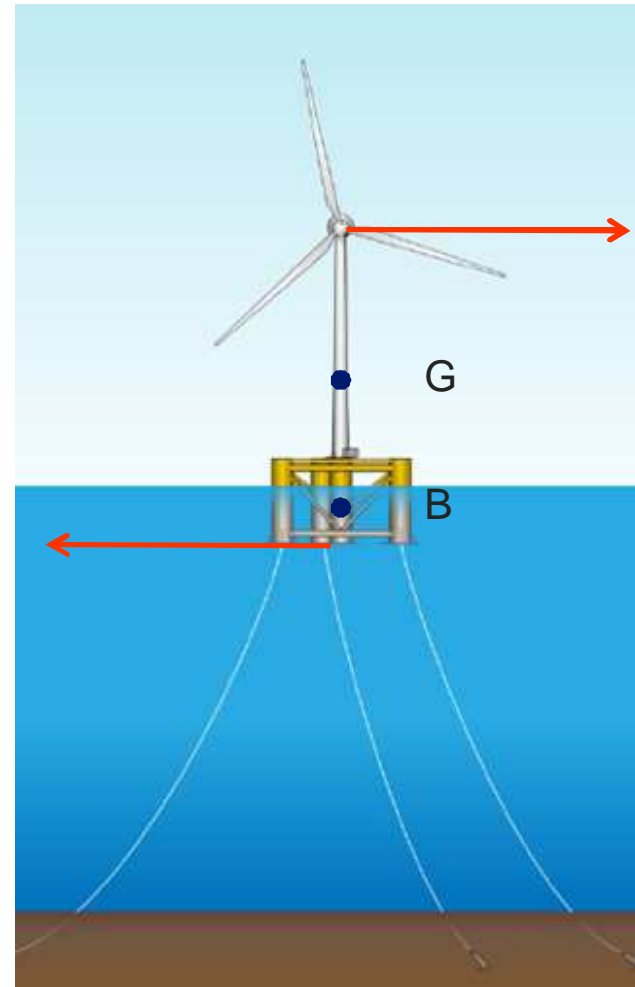


STABILITY OVERVIEW

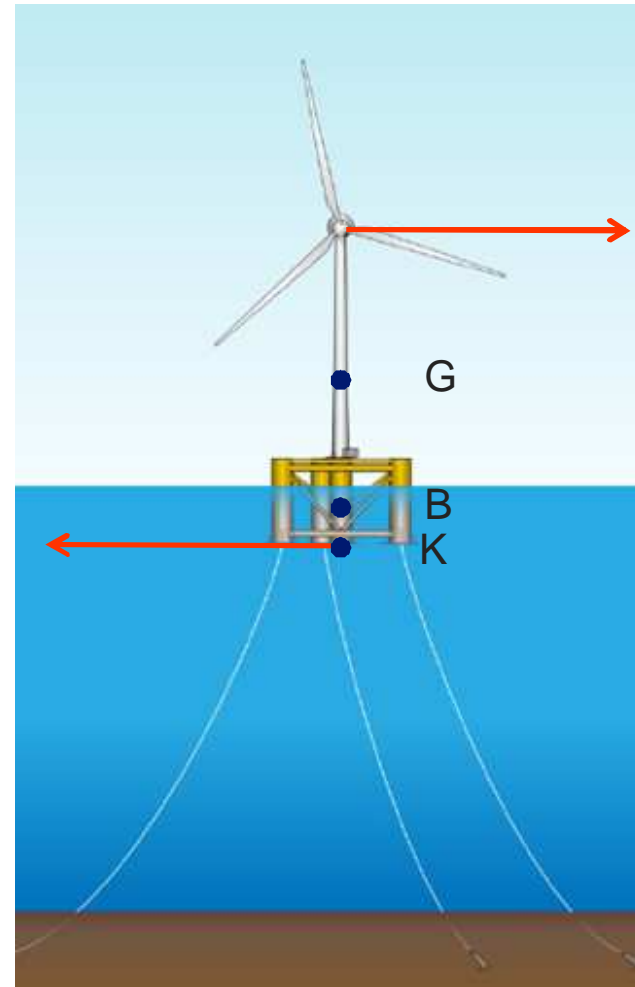
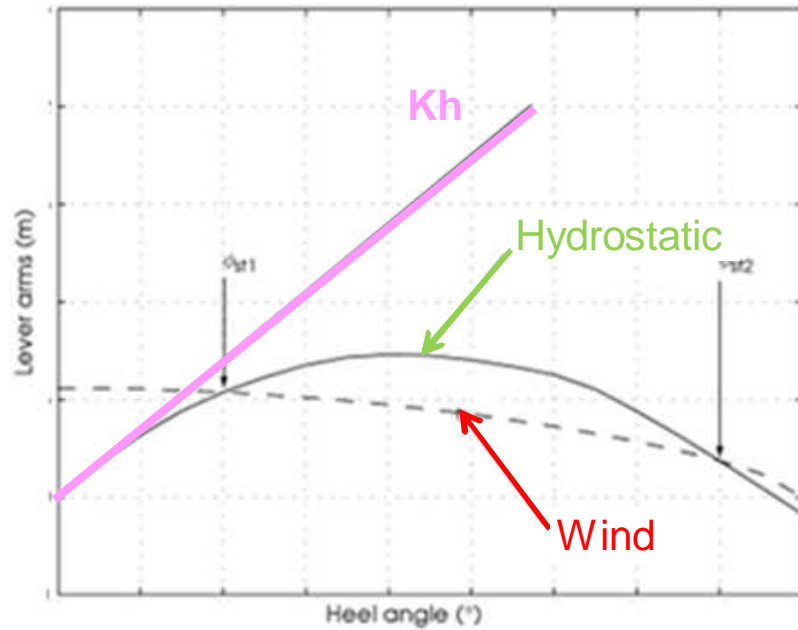
- **Stability consists of comparing**
 - Heeling moment due to wind
 - Restoring forces due to buoyancy

- **Wind heeling moment**
 - Rotor thrust
 - Point of application

- **Buoyancy restoring moment**
 - Position of center of buoyancy B
 - Position of center of gravity G
 - **Water plane area**

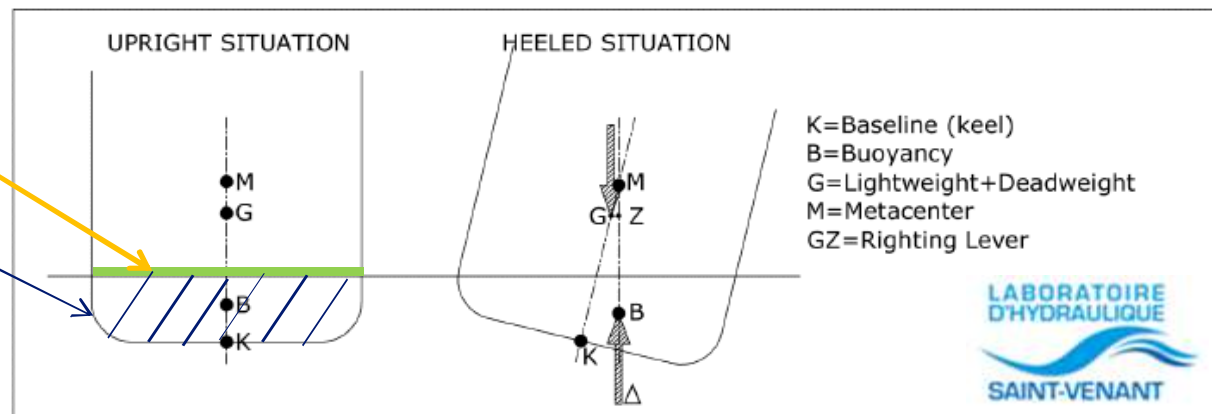


STABILITY OVERVIEW



- Hydrostatic stiffness

$$K_H = \rho V g \left(KB - KG + \frac{I}{V} \right)$$



STABILITY APPLICATION

- SPAR SOLUTION

$$K_H = \rho V g \left(\underbrace{KB - KG}_{\text{Low contribution}} + \underbrace{\frac{I}{V}}_{\sim \text{big}} \right)$$

small

KB-KG=GB Low contribution



Stability from the distance between
Center of Gravity and Center of buoyancy



STABILITY APPLICATION

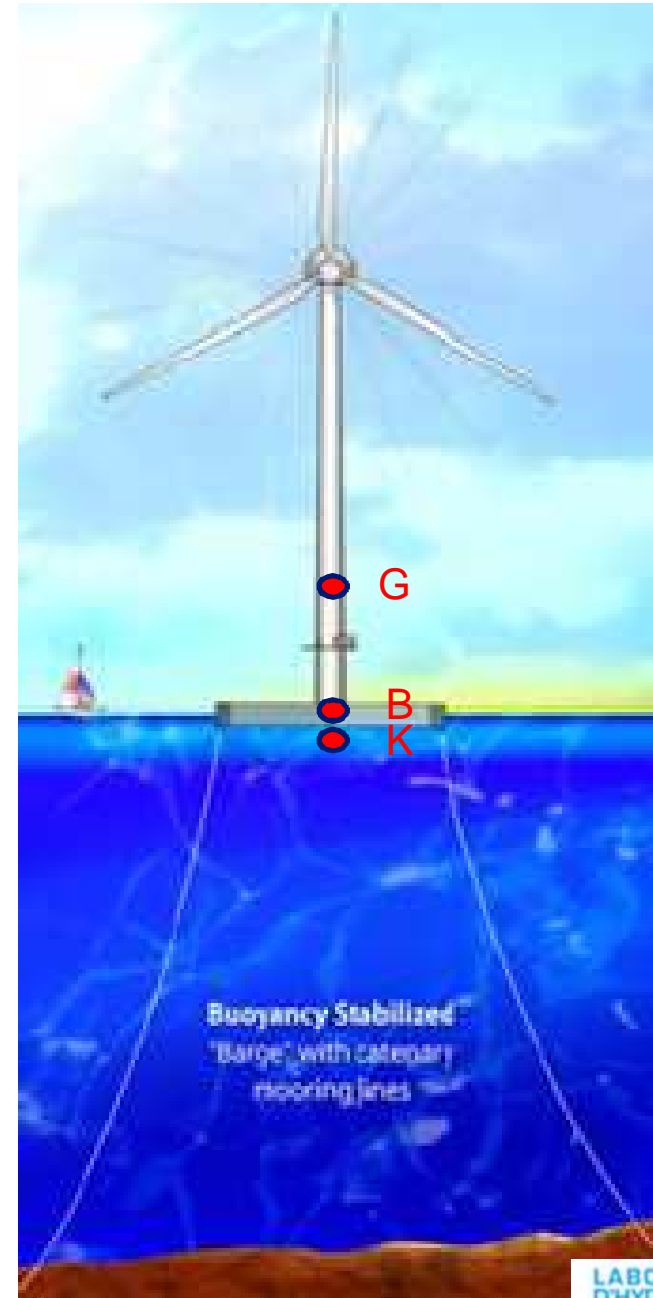
- BARGE SOLUTION

$$K_H = \rho V g \left(\underbrace{KB - KG}_{KB-KG=GB < 0} + \underbrace{\frac{I}{V}}_{\sim \text{small}} \right)^{\text{Big}}$$

KB-KG=GB < 0
High contribution



Stability from the size of the water plane area



Buoyancy Stabilized "Barge" with catenary mooring lines

STABILITY APPLICATION

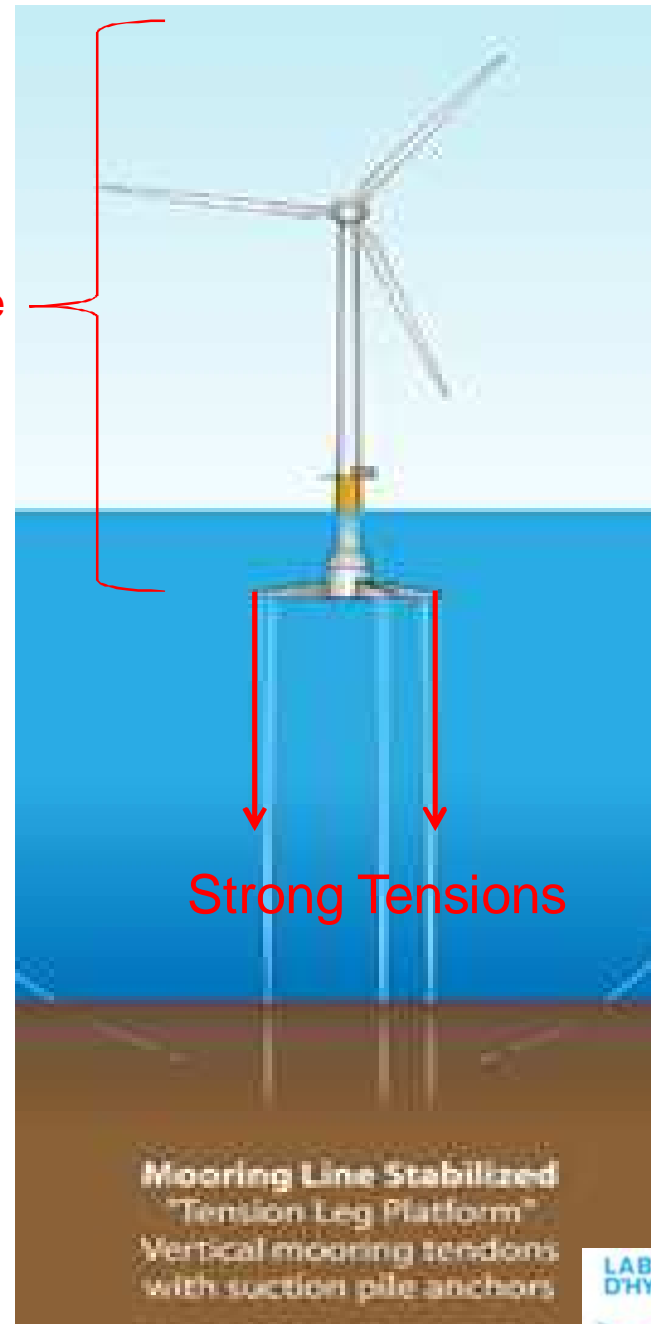
- TLP SOLUTION

$$K_H = \rho V g \left(\underbrace{KB - KG}_{KB-KG=GB} + \underbrace{\frac{I}{V}}_{\text{Contribution}} \right)$$



Stability from the tendons

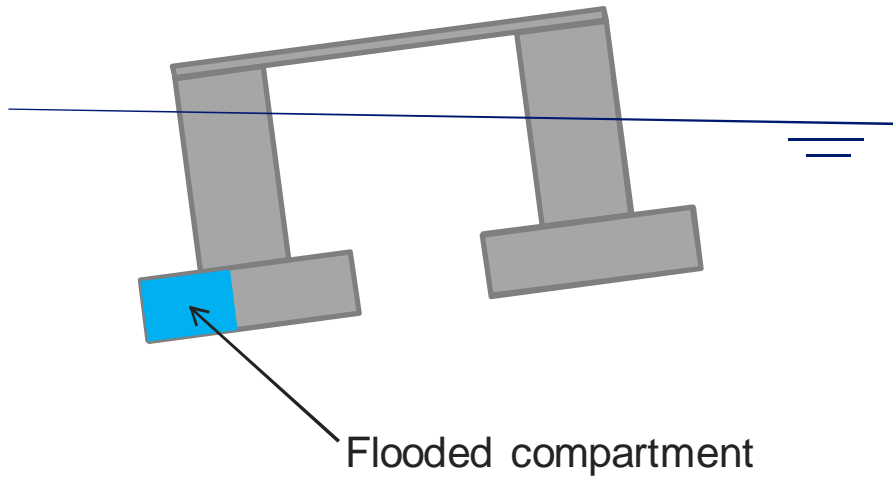
Unstable



STABILITY

ADDITIONAL CASES

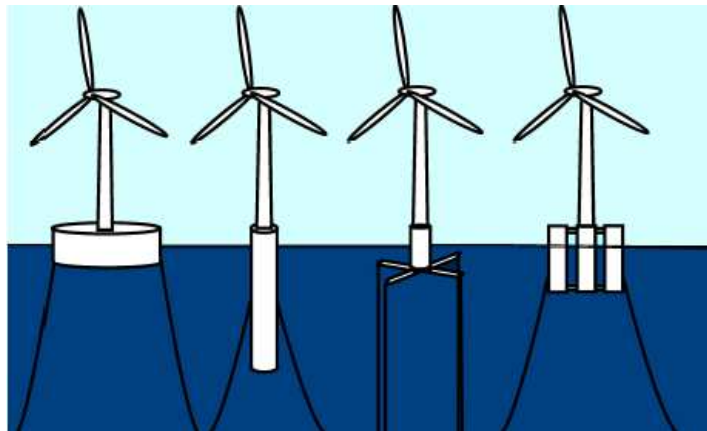
- In addition, you need to consider
 - Damaged cases, when the floater is partially flooded
 - Towing and installation phases



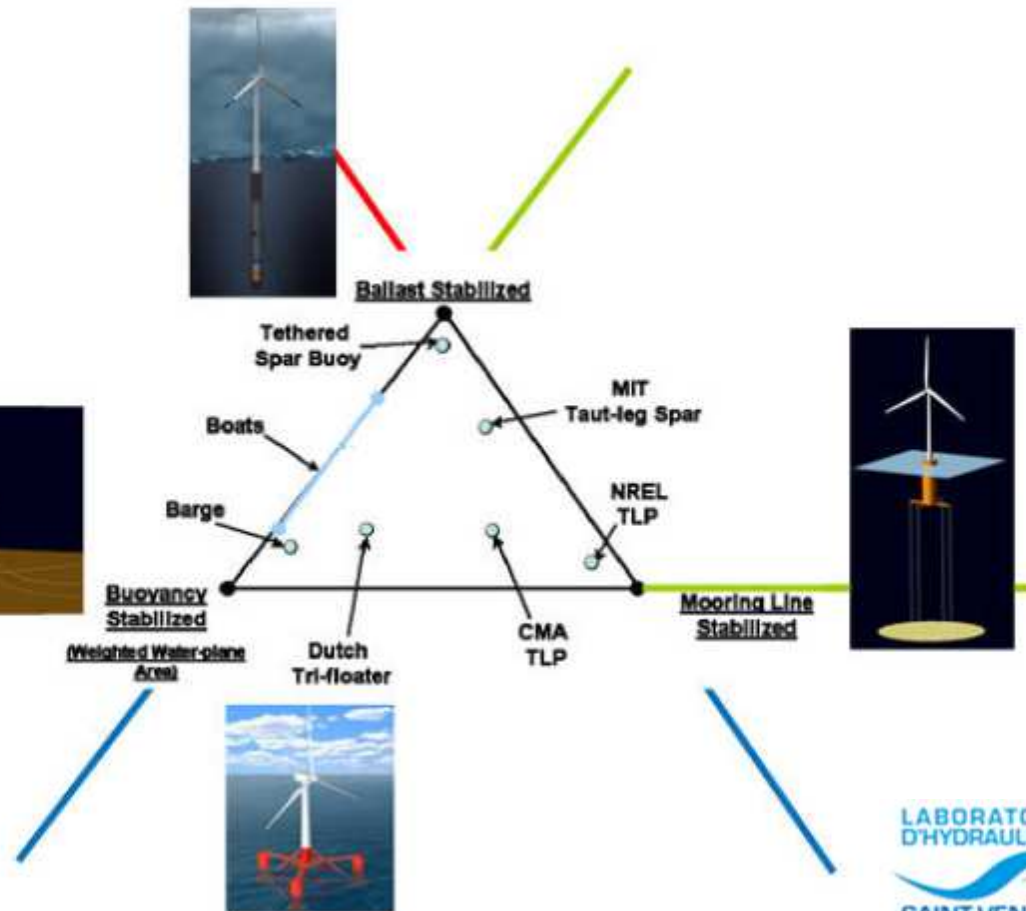
FLOATING PLATFORMS

TYPES OF FLOATERS

- Generally, 4 types of floaters are considered

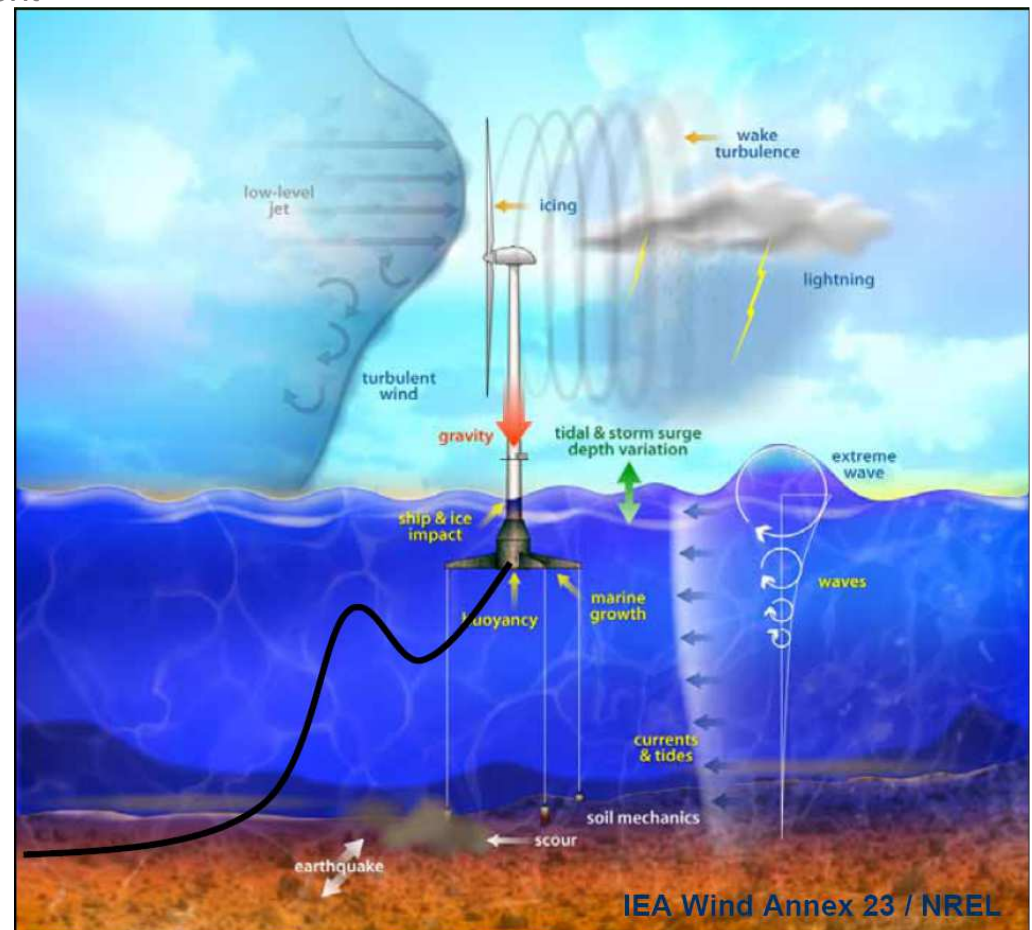


BARGE SPAR TLP SEMI-SUB



FLOATING PLATFORMS DESIGN PROCESS

- **Metocean study**
- **Stability**
 - Platform counterbalance wind heeling moment
- **Motions**
 - Maximum motions & accelerations to insure system resistance
 - Maximum motions for power performance
- **Station-Keeping**
 - Insure IAC security
 - Avoid drift
- **Installation**
 - Is the platform easy to build / install / maintain



MOTIONS AND ACCELERATIONS ANALYSIS

OVERVIEW

- Floating offshore wind platforms motions due to

- Wind : stochastic phenomenon
- Waves : irregular sea states
- Current
- Platform / Structure natural modes

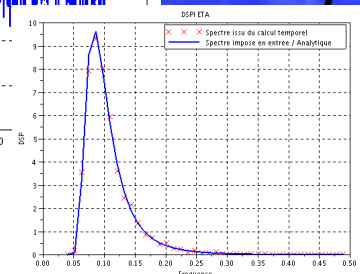
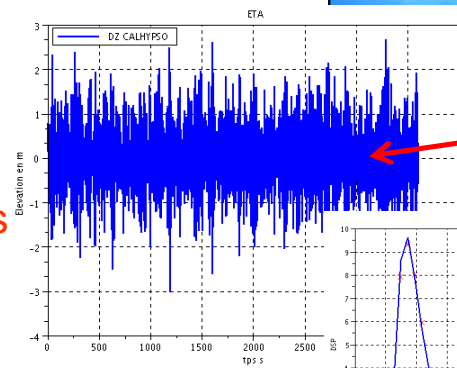
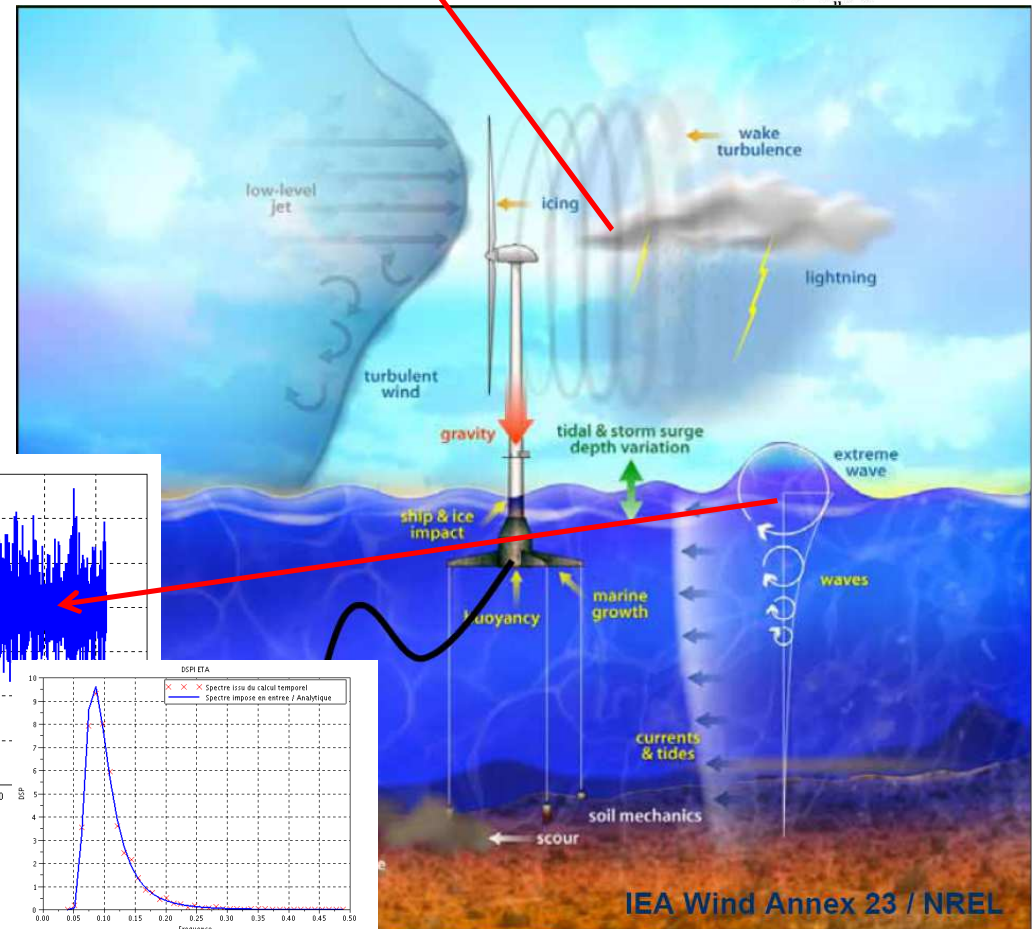
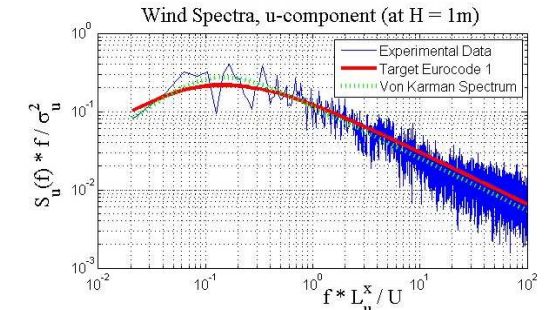
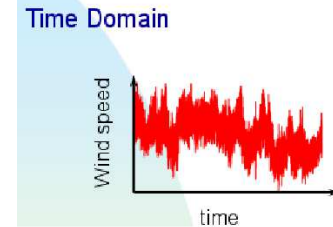
➡ Non-linear moorings

➡ Non-linear forces

- Need to perform a numerical analysis

- Aerodynamic models
- Hydrodynamic models
- Structural models

➡ Keep in mind :
~10 000 load cases



MOTIONS AND ACCELERATIONS ANALYSIS

MODELLING APPROACH - HYDRODYNAMICS – POTENTIAL FLOW

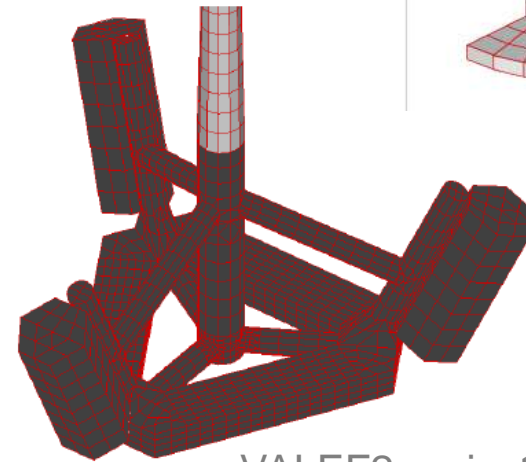
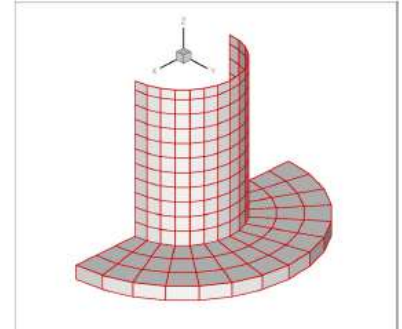
- **Hydrodynamic models used in most of the FOWT projects**

- Potential flow + no viscosity
 - Irrotational
 - No drag forces
- Linear hypothesis
 - Small waves
 - Small motions

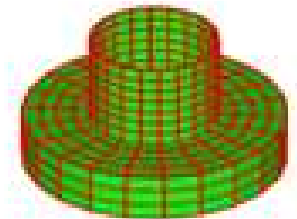
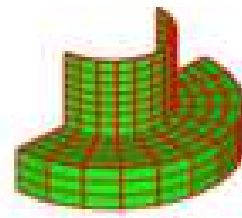
- **Differences between bottom fixed and floating**

- Need for buoyancy/stability leads to « Large » structures
 - ➡ **Thin bodies hypothesis not fully respected**
- Structure experiences significant motions
 - ➡ **Need to model waves – motions interactions**
- Wave-Structure interaction

➡ **Diffraction / Radiation approach**



VALEF2 project



MOTIONS AND ACCELERATIONS ANALYSIS

MODELLING APPROACH – HYDRODYNAMICS - POTENTIAL FLOW

- **Numerical tools**

- Commercial
 - WAMIT
 - DIODORE
 - HYDROSTAR
 - AQWA
- Non-commercial
 - NEMOH (Free - Open Source – Ecole Centrale Nantes)

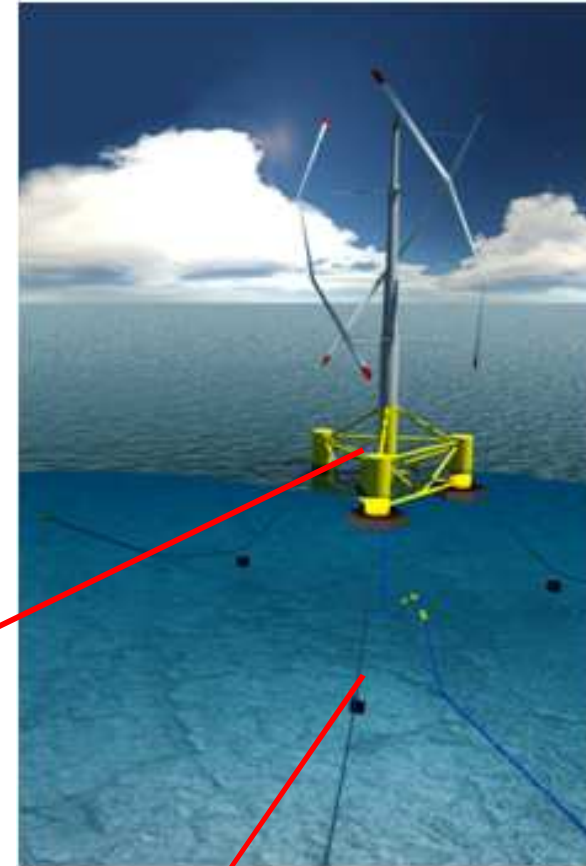
- **Outputs**

- Added mass
- Radiation Damping
- Hydrodynamic forces
- Hydrostatic stiffness

○ Waves induced by motion

○ Forces

○ Buoyancy



Equation Of Motion

$$(\overset{\text{Buoyancy}}{M} + \overset{\text{Waves induced by motion}}{M_A(\omega)})\ddot{x} + (\overset{\text{Waves induced by motion}}{D} + \overset{\text{Waves induced by motion}}{B(\omega)})\dot{x} + (\overset{\text{Buoyancy}}{K} + \overset{\text{Buoyancy}}{K_H})x = \overset{\text{Forces}}{F_e}$$

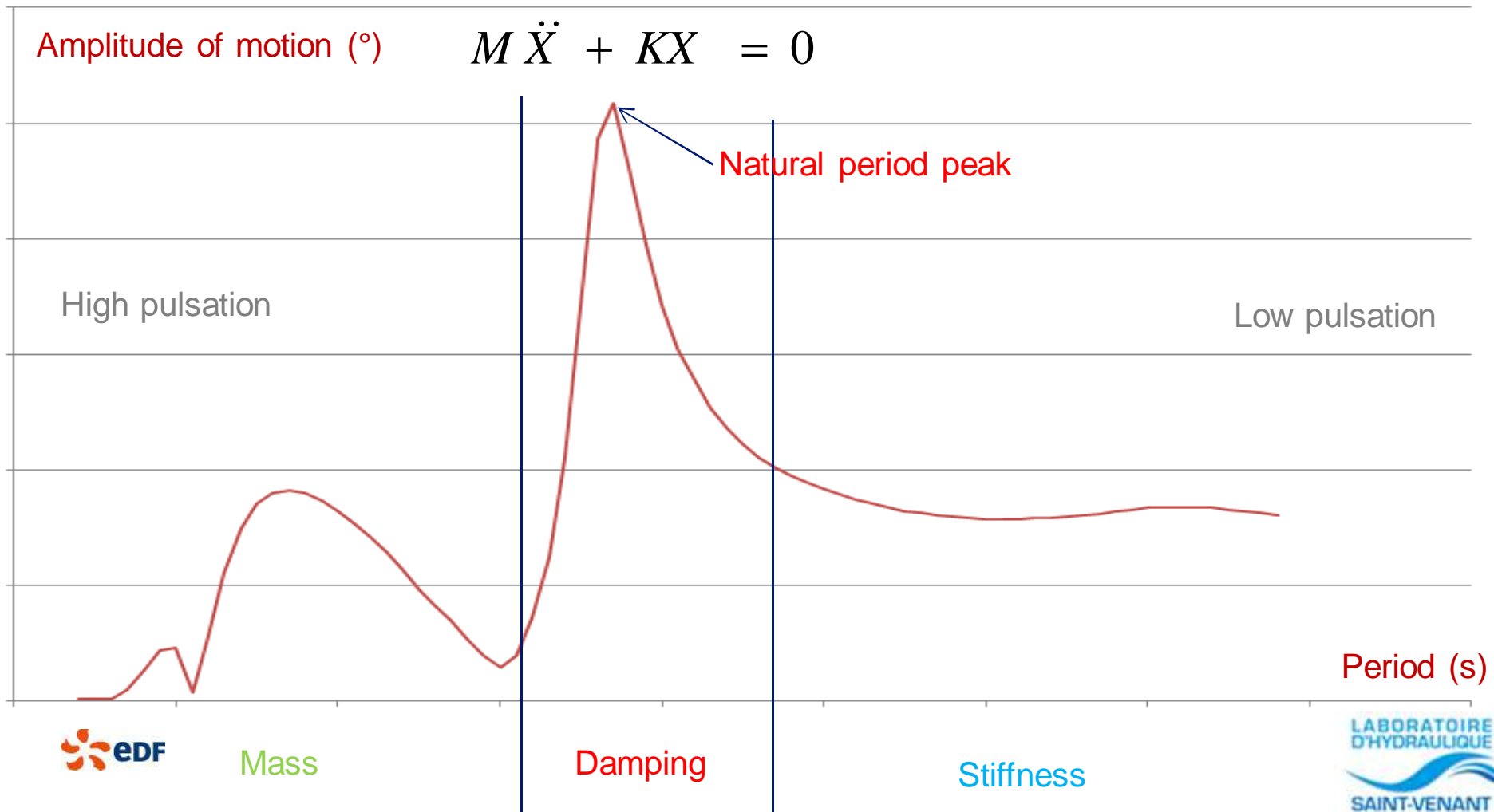
➔ 6 degrees of freedom equation

MOTIONS AND ACCELERATIONS ANALYSIS

MODELLING APPROACH – FREQUENCY DOMAIN MODELLING

$$(M + M_A(\omega))\ddot{x} + (D + B(\omega))\dot{x} + (K + K_H)x = F_e$$

Pitch - 180°



MOTIONS AND ACCELERATIONS ANALYSIS

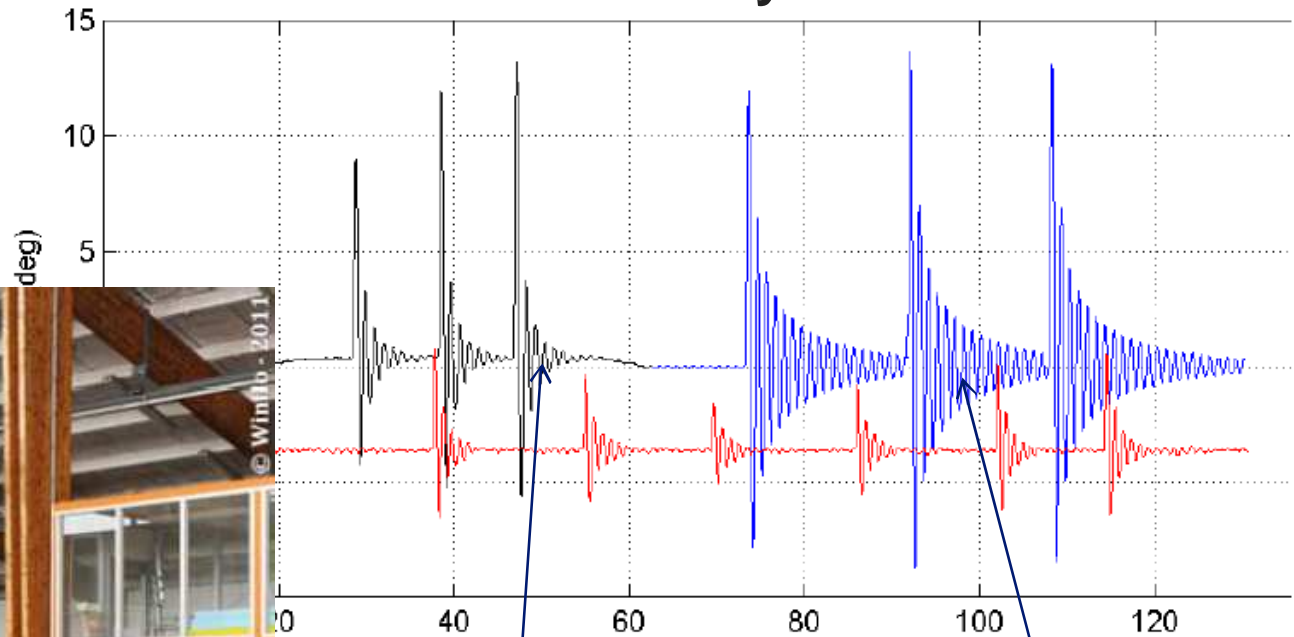
AERO/HYDRO COUPLING – DAMPING

- Aerodynamic Damping : WINFLO project

➔ Influence on motions
Control strategy



Pitch decay test



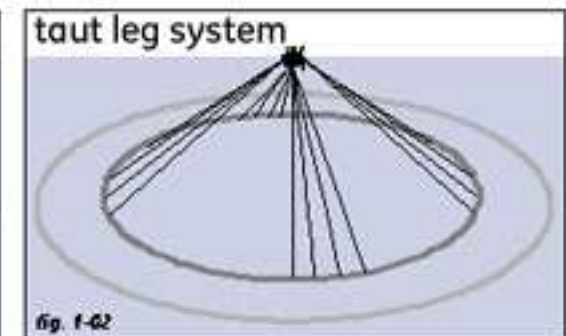
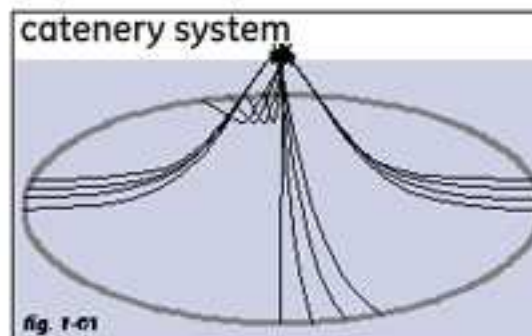
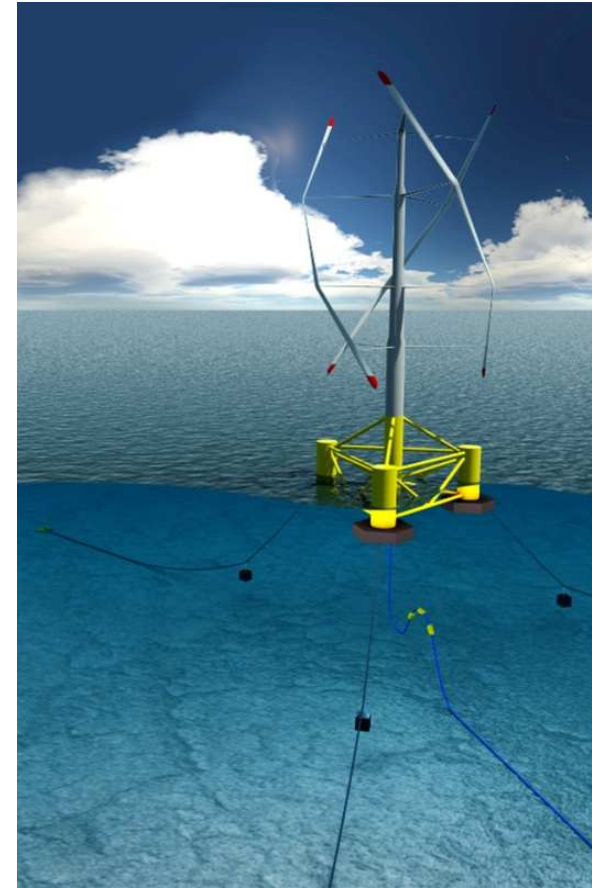
Aero + Hydro

Hydro Only

STATION KEEPING ANALYSIS

TYPE OF MOORING SYSTEM

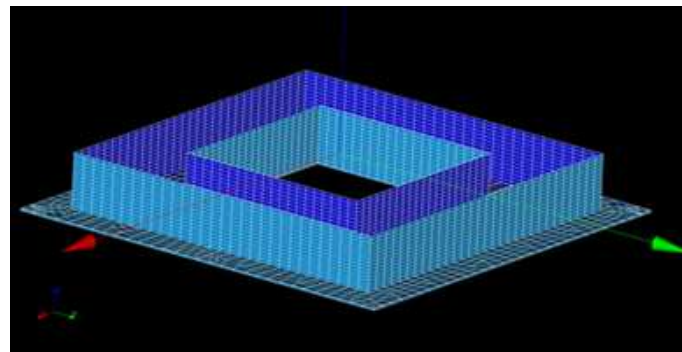
- **Catenary lines**
 - Weight
 - Large Mooring radius
 - Several times water depth
 - ~ 400 m – 800 m
 - Farm application?
 - Used for the 5 multi MW FOWT projects
- **TLP**
 - Tension
 - Low Mooring radius
 - ~ 50 m
 - Good for farm application
- **Taut or semi-taut lines**
 - Intermediate solution
 - Generally with synthetic rope



STATION KEEPING SYSTEM

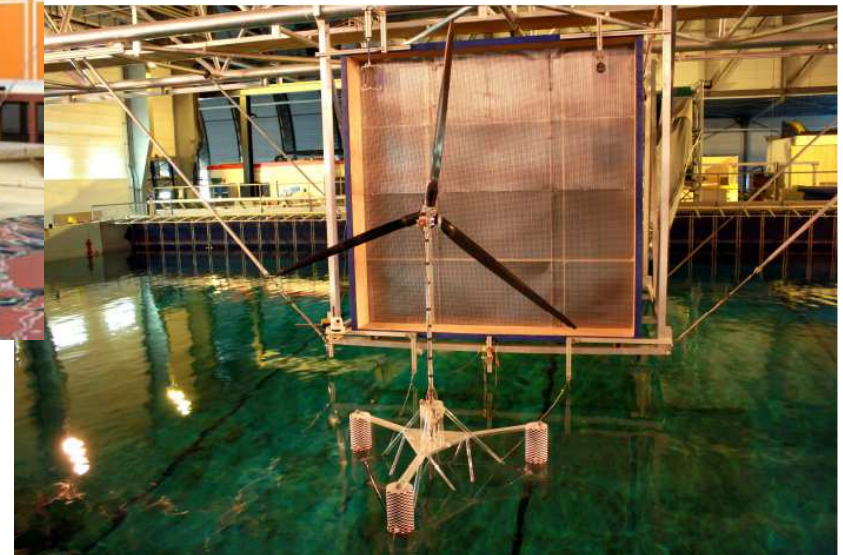
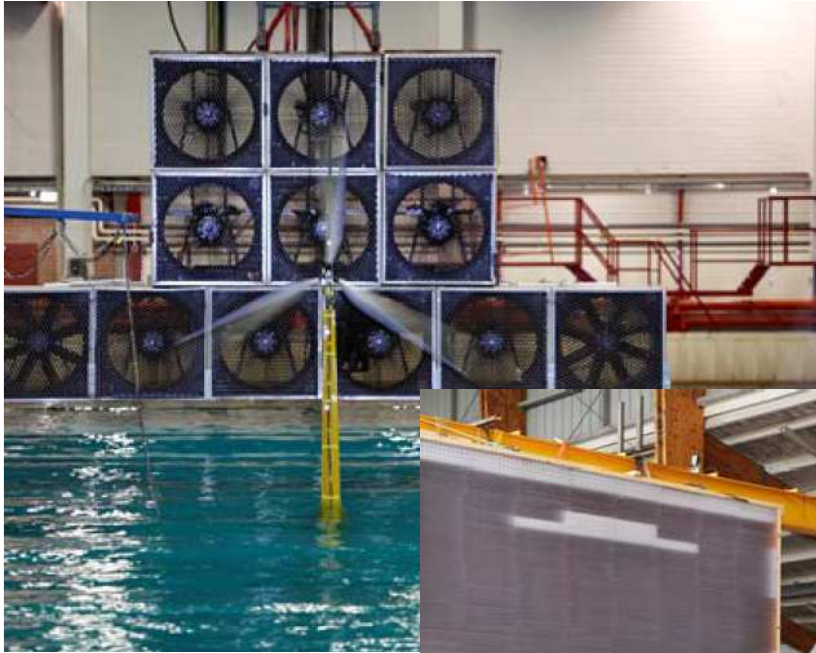
APPLICATION TOOLS

- **All FOWT projects use mainly time domain approach to design their system**
 - Motion and acceleration analysis
 - Mooring sizing
- **Some numerical tools from Oil&Gas and Onshore wind have been adapted and coupled**
 - Orcaflex / No aerodynamic module
 - Deeplines Wind
 - Bladed
 - FAST (free & OpenSource) / No dynamic mooring
- **Keep in mind that another software is often necessary to solve the Diffraction/Radiation problem**



BASIN TESTS

FULL SYSTEM SCALING



- **Froude scaling**
 - Well adapted for wave-structure interaction
 - Aerodynamics very sensitive to Reynolds number
 - Hard (impossible) to scale
 - Geometry
 - Thrust
 - Rotor speed and wind velocity
- **Typical scale**
 - Between 1/20th and 1/50th
 - Water depth : 100m => 2m to 5m
 - Catenary lines ~ 600m => 10m to 30m



BASIN TESTS

OTHER STRATEGIES FOR FULL SYSTEM MODELLING

- **Need for full system behavior assesment**
 - Froude scaling / Reynolds scaling
 - Multi-MW prototypes Expensive & time consuming
- **Software In the Loop (SIL)**
 - Froude scaling for the mast, floater and mooring
 - Fan on top of mast, driven by an aerodynamic software

➔ **Experimental validation of hydrodynamic behavior**

- **Wind Tunnel tests**
 - Reynolds scaling
 - Hexapod

➔ **Experimental validation of aerodynamic loads under wave induced motions**

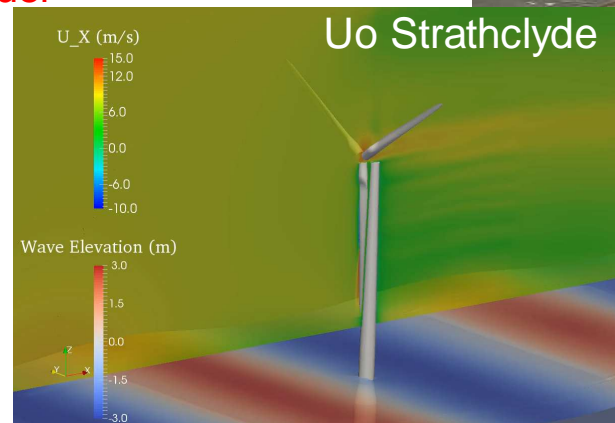
- **CFD**
 - Global system modelling
 - High CPU cost



PdM – LIFE50+ project

UCC

- LeanWind project



INSTALLATION



INSTALLATION - SPAR



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INSTALLATION - SEMISUBMERSIBLE



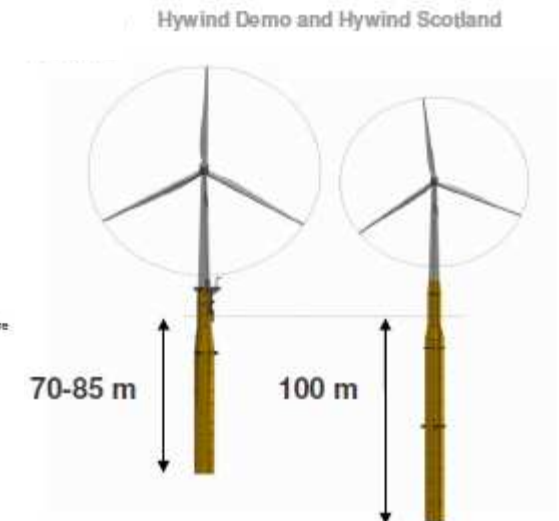
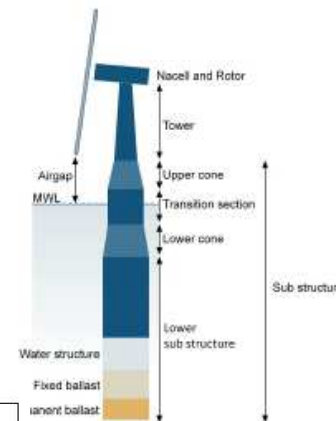
NEXT STEP FOR FLOATING - HYWIND SCOTLAND

- “Roadmap” Hywind-Statoil

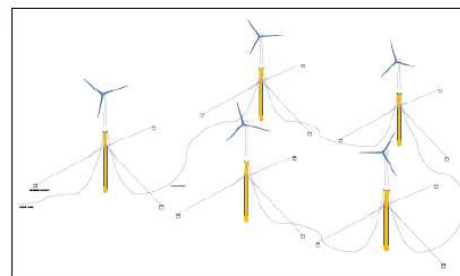


- Hywind Scotland Pilot Park (2013 – 2017)

	Hywind Scotland
Installed capacity (5 WTGs)	30 MW
Area (sea level)	~4 km ²
Water depth	95-120 m
Average wind speed (@100 m)	10.1 m/s
Mean waves, Hs	1.8 m
Offshore export cable length	Ca.30 km
Onshore cable length	Ca.2-3 km
Transmission voltage	33 kV
Mooring	Pre-laid chains
Anchor	Suction



Winner of Scottish Floating Offshore Wind Call for Tender (2013)



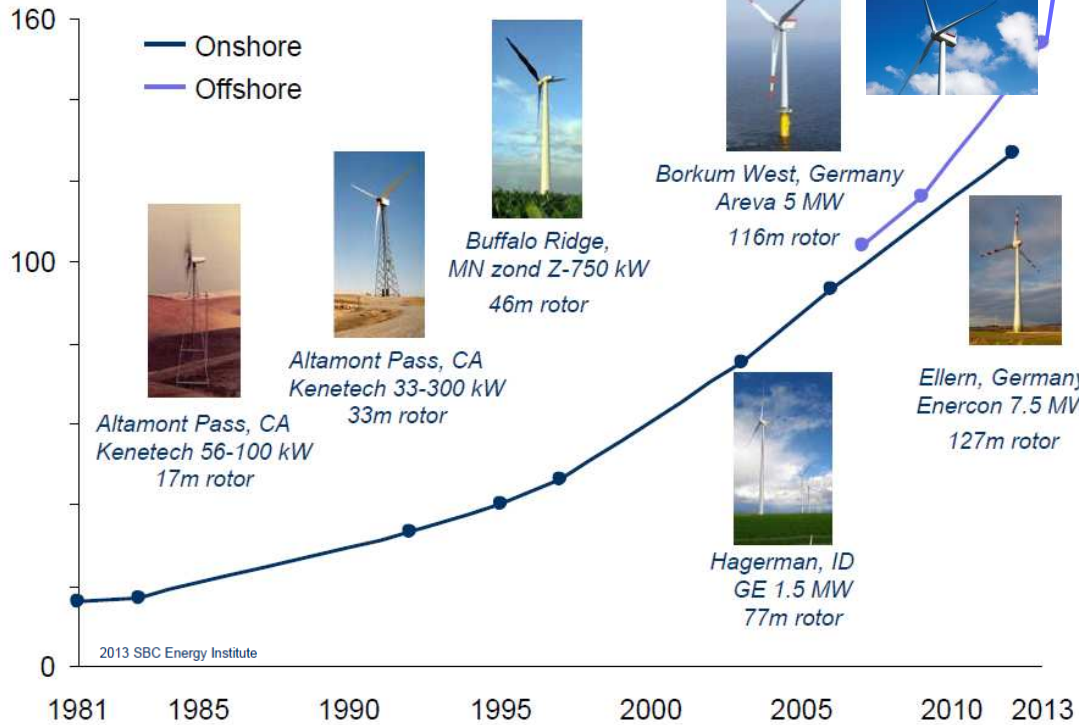
SOME CHALLENGES FOR OFFSHORE WIND



TURBINE SIZE AND CONTROLLER

EVOLUTION OF THE TURBINE DIAMETER

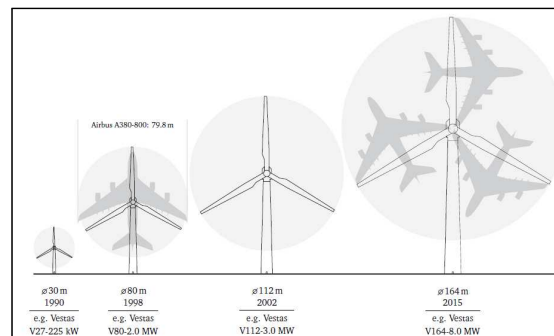
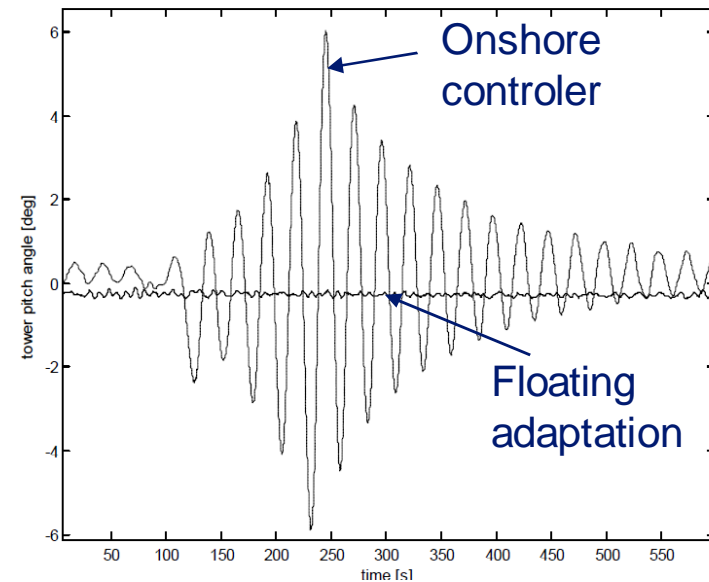
Diameter in meters



Wind induced motion damping



Fatigue reduction



FLOATING WIND

STILL AT A R&D STAGE

- **Need for stability**
 - Reduce turbine thrust
 - Increase turbine tolerance to tilt
 - Innovative floater solution

- **Flexible system design**
 - Mooring lines length
 - Mooring lines materials
 - Export cable / Offset of the FOWT

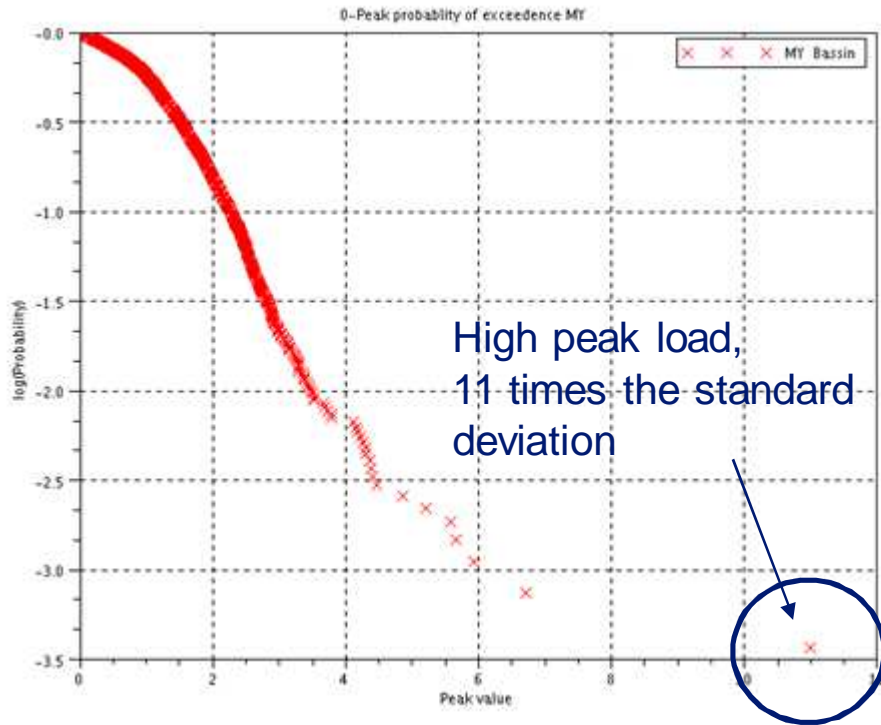
- **Projects technical de-risking**
 - Global behavior of a complex system
 - Basin test strategy ?
 - CFD ?

IMAGE

HYDRODYNAMIC LOADS

BETTER ESTIMATION FOR BETTER DESIGN

- Ringing loads observed on Gravity Based Foundations
 - Ringing is a high order hydrodynamic phenomenon
 - Induces very high loads ⇔ Design for Extrem storms



- TLP structures can also experience ringing loads
 - Example : Heidrun Tension Leg Platform
 - Impact on tendons design



- ➔ Development of fully nonlinear hydrodynamic models (Potential flow / Navier-Stokes)
- ➔ High CPU cost/High research cost



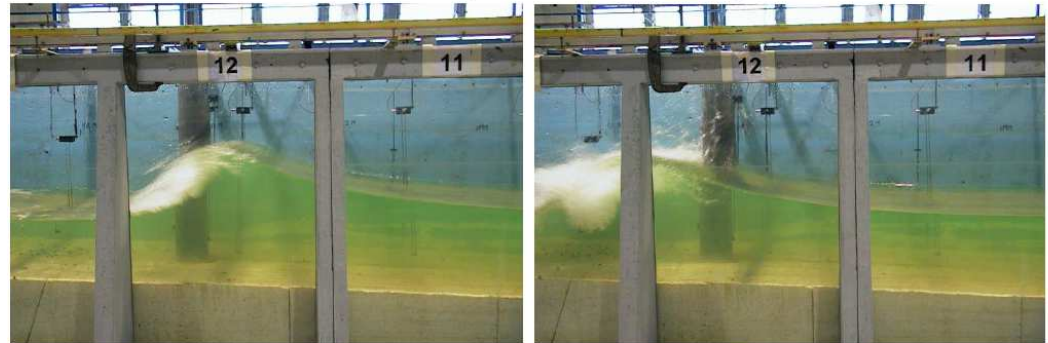
HYDRODYNAMIC LOADS

BETTER ESTIMATION FOR BETTER DESIGN

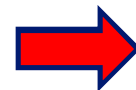
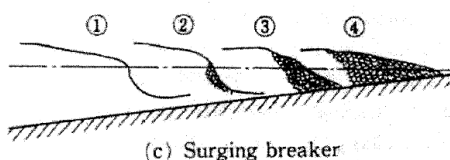
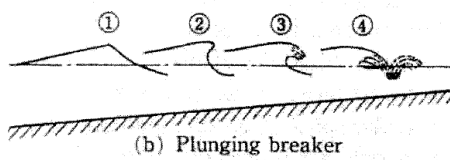
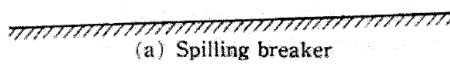
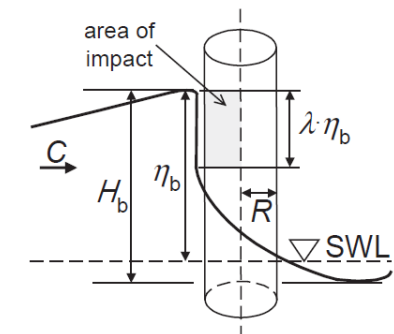
- **Breaking waves**
 - When steepness increase until a level of about 14%
 - Impact loads
 - Complex fluid mechanics problem



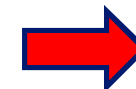
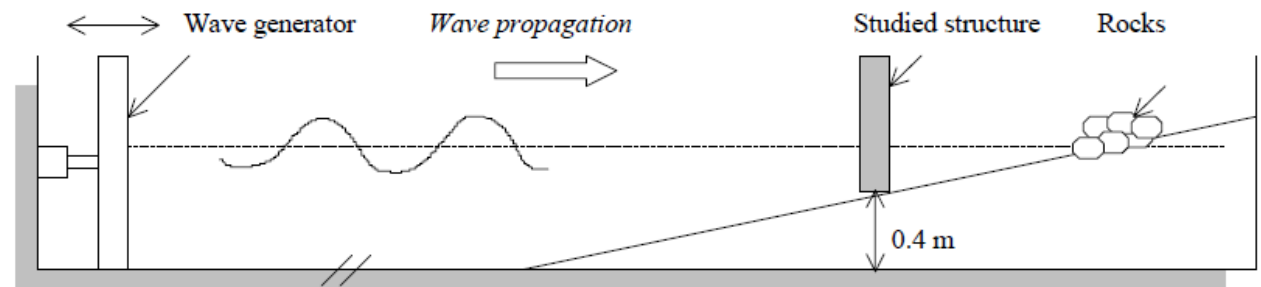
Test EOL59 : bottom slope 5% - $d_{\text{offshore}} = 0.8 \text{ m}$ - $T = 2.4 \text{ s}$ - $H_{\text{offshore}} = 0.288 \text{ m}$



Test EOL107 : bottom slope 2.5% - $d_{\text{offshore}} = 1.0 \text{ m}$ - $T = 1.6 \text{ s}$ - $H_{\text{offshore}} = 0.280 \text{ m}$



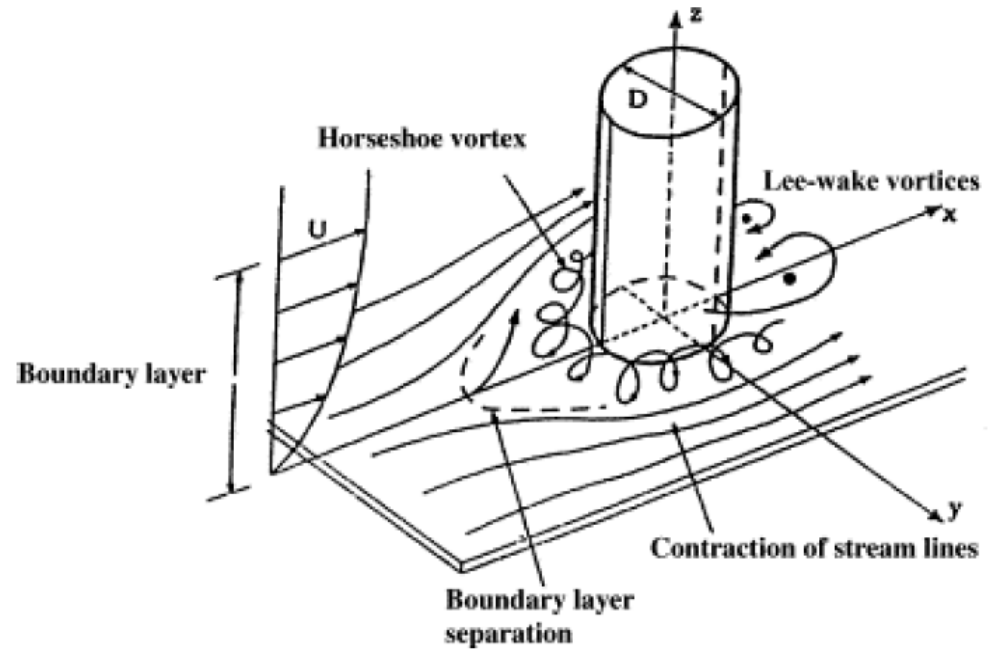
Needs for experimental work



Or CFD (VoF, SPH methods...)

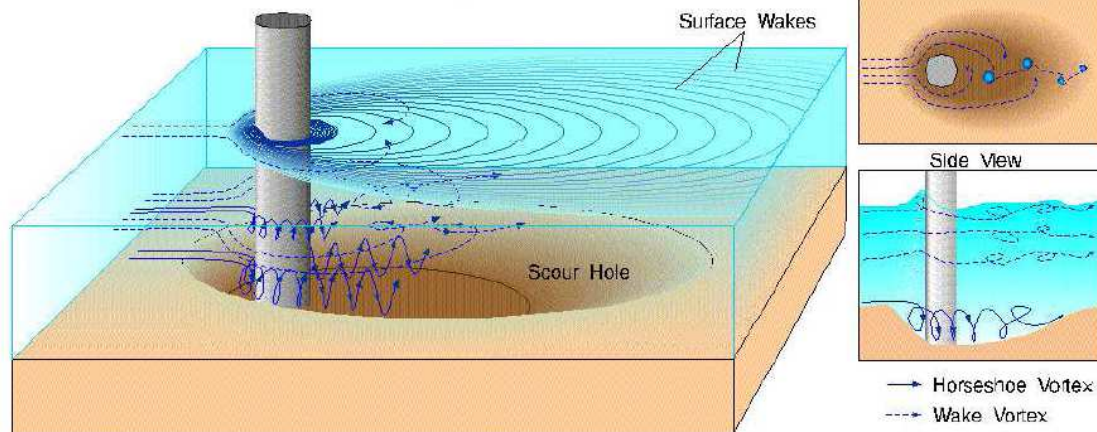
SCOURING

- **Sediment convection by fluid**
 - Waves
 - Currents
- **Scouring issues**
 - Can be very critical
 - Modelling
 - Protection



Loss of stability for the foundation
Stiffness – Natural frequencies

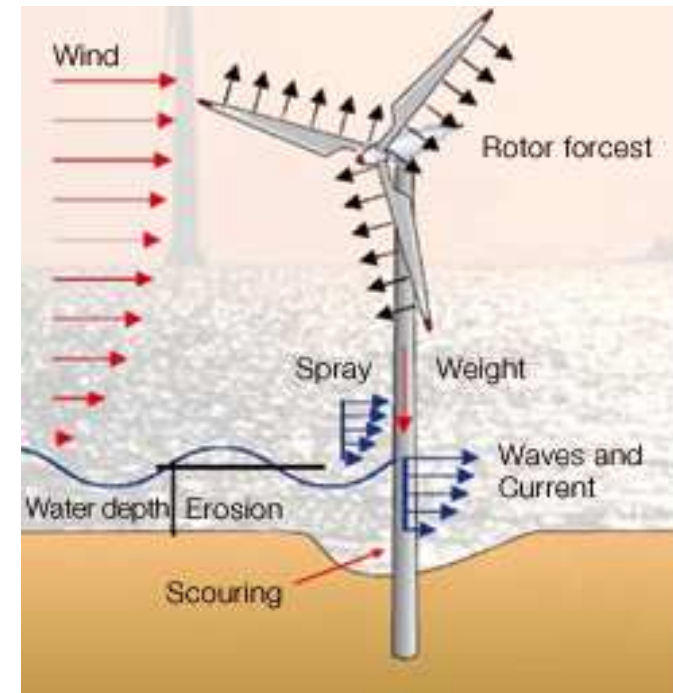
Horseshoe and Wake Vortices around a Cylindrical Element



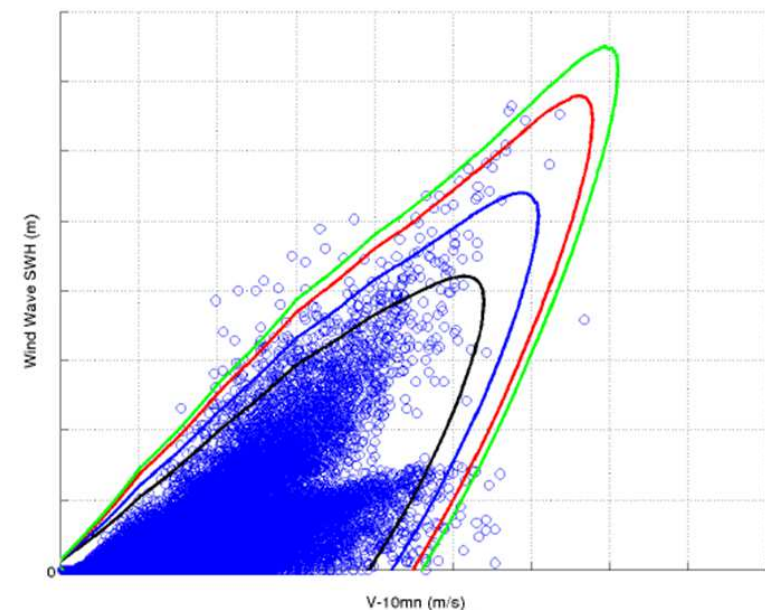
DESIGN METHODOLOGY

DESIGN LOAD CASES (DLC)

- Very high number of load cases to design an OWT
 - ~ 20000 DLCs
 - Fatigue + Extreme events
 - Standards and Guidelines : IEC, DNV, GL, ABS...
- Due to the number of parameters
 - Wind
 - Direction / Intensity / Turbulence
 - Wave
 - Direction / Height / Period / Spectrum
 - Turbine
 - Start up / Shut down / Grid loss
 -
- Design strategy
 - Response based design ?
 - Fatigue assesment



Wind and Waves induced Force&Moment in the same order of magnitude



PROJECT ACCEPTABILITY

CRITICAL ISSUE IN THE DEVELOPEMENT

- YYY
 - XXX

IMAGE

A photograph of an offshore wind turbine. The turbine has three white blades with red tips, mounted on a white tower. The tower is supported by a yellow jacket structure with three legs extending into the water. The background shows a vast blue ocean and a distant coastline with buildings and hills under a clear sky.

THANK YOU